

Principled Programming

Introduction to Coding in Any Imperative Language

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Emeritus Professor

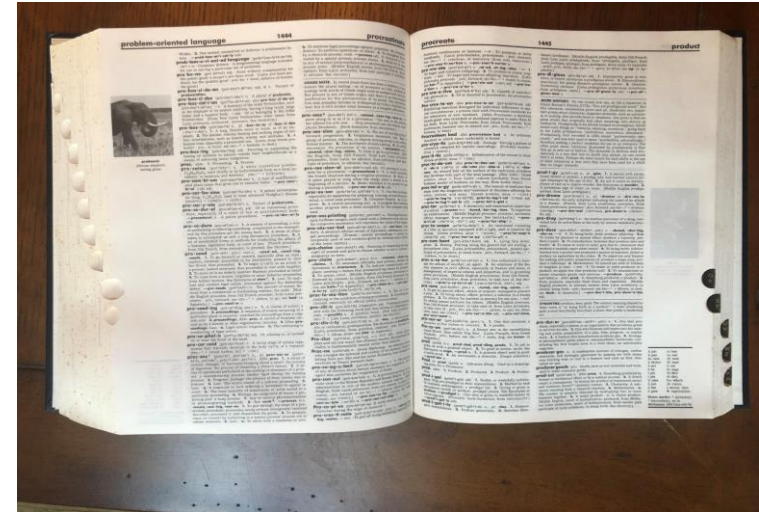
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Binary Search

If you want to find the definition of the word **proboscis** in a 512-page dictionary, you wouldn't use Sequential Search starting on the first page, say, with **aardvark**. Rather, you would start roughly in the middle. From there, you would:

- Repeatedly halve the portion of the dictionary that remains under consideration, doing so by looking at the middle page of the region in hand, and discarding whichever half is revealed thereby to not contain **proboscis**.
- Once the search has been narrowed to a single page, you would look on that page to see if **proboscis** is there.
- If it is, you found its definition; otherwise, it isn't in the dictionary.



The method is called **Binary Search**, and is an example of a **Divide and Conquer algorithm**. Binary Search is astoundingly fast.

Application: Search for a value v in an **unordered** array $A[0..n-1]$.

```
#.Given array  $A[0..n-1]$ ,  $n \geq 0$ , and value  $v$ , let  $k$  be an index of  $A$   
#   where  $A[k] == v$ , or  $n$  if there is no  $v$  in  $A$ .
```

 **A statement-comment says exactly what code must accomplish, not how it does so.**

Application: Search for a value v in an **ordered** array $A[0..n-1]$.

```
#.Given ordered array  $A[0..n-1]$ ,  $n \geq 0$ , and value  $v$ , let  $k$  be an index of  $A$   
#   where  $A[k] == v$ , or  $n$  if there is no  $v$  in  $A$ . */
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 **A statement-comment says exactly what code must accomplish, not how it does so.**

Application: Search for a value v in an ordered array $A[0..n-1]$.

```
# Given ordered array  $A[0..n-1]$ ,  $n \geq 0$ , and value  $v$ , let  $k$  be an index of  $A$   
#   where  $A[k]=v$ , or  $n$  if there is no  $v$  in  $A$ .  
 $k = 0$   
while ( $A[k] \neq v$ ) and ( $k < n$ ):  $k += 1$ 
```

 **Master stylized code patterns, and use them.**

Sequential search works, but ignores the order. We can do better.

Application: Search for a value v in an ordered array $A[0..n-1]$.

Given ordered array $A[0..n-1]$, $n \geq 0$, and value v , let k be an index of A
 # where $A[k] == v$, or n if there is no v in A .

_____ **while** _____ : _____

Coding order
(1) body
(2) termination
(3) initialization
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(5) boundary conditions

 **If you “smell a loop”, write it down.**



Application: Search for a value v in an ordered array $A[0..n-1]$.

Given ordered array $A[0..n-1]$, $n \geq 0$, and value v , let k be an index of A
 # where $A[k]==v$, or n if there is no v in A .

while _____: _____

 **Invent (or learn) diagrammatic ways to express concepts.**



Application: Search for a value v in an ordered array $A[0..n-1]$.

Given ordered array $A[0..n-1]$, $n \geq 0$, and value v , let k be an index of A
 # where $A[k] == v$, or n if there is no v in A .

```

while _____:
    _____

```

👉 To get to **POST** iteratively, choose a **weakened POST** as **INVARIANT**.



Application: Search for a value v in an ordered array $A[0..n-1]$.

Given ordered array $A[0..n-1]$, $n \geq 0$, and value v , let k be an index of A
 # where $A[k] == v$, or n if there is no v in A .

```
L = _____; R = _____
while _____: _____
  _____
```

 Introduce program variables whose values describe “state”.



VARIANT: R-L
INVARIANT

Application: Search for a value v in an ordered array $A[0..n-1]$.

Given ordered array $A[0..n-1]$, $n \geq 0$, and value v , let k be an index of A
 # where $A[k] == v$, or n if there is no v in A .

```
L = _____; R = _____
while _____:
    if _____: _____
    else: _____
_____
```

👉 **A Case Analysis in the loop body is often needed for characterizing different ways in which to decrease the loop variant while maintaining the loop invariant.**



VARIANT: R-L
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Application: Search for a value v in an ordered array $A[0..n-1]$.

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# Given ordered array  $A[0..n-1]$ ,  $n \geq 0$ , and value  $v$ , let  $k$  be an index of  $A$ 
# where  $A[k] == v$ , or  $n$  if there is no  $v$  in  $A$ .
```

```
L = _____; R = _____
```

```
while _____:
```

```
    if _____:
```

```
        R = _____ # Select left "half".
```

```
    else:
```

```
        L = _____ # Select right "half".
```

```
_____
```

👉 **A Case Analysis in the loop body is often needed for characterizing different ways in which to decrease the loop variant while maintaining the loop invariant.**



VARIANT: R-L
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# where  $A[k] == v$ , or  $n$  if there is no  $v$  in A.
```

```
L = _____; R = _____
```

```
M = _____ # Compute "midpoint".
```

```
while _____:
```

```
    if _____:
```

```
        R = _____ # Select left "half".
```

```
    else:
```

```
        L = _____ # Select right "half".
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```
_____
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👉 **A Case Analysis in the loop body is often needed for characterizing different ways in which to decrease the loop variant while maintaining the loop invariant.**



VARIANT: R-L
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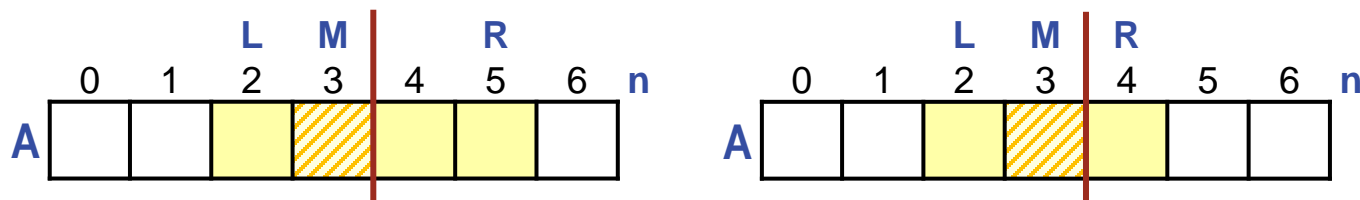
```
        R = _____ # Select left "half".
```

```
    else:
```

```
        L = _____ # Select right "half".
```

```
_____
```

If you object to $A[L..R]$ straddling the midpoint of $A[0..n-1]$, understand that in "schematic diagrams", the exact locations of boundaries are immaterial.



Application: Search for a value v in an ordered array $A[0..n-1]$.

```
# Given ordered array A[0..n-1],  $n \geq 0$ , and value  $v$ , let  $k$  be an index of A
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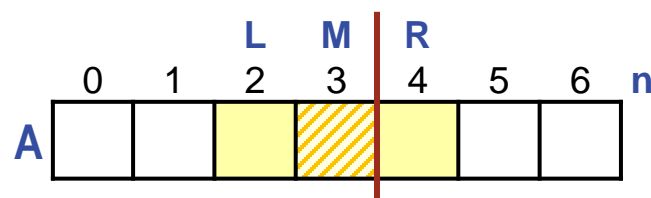
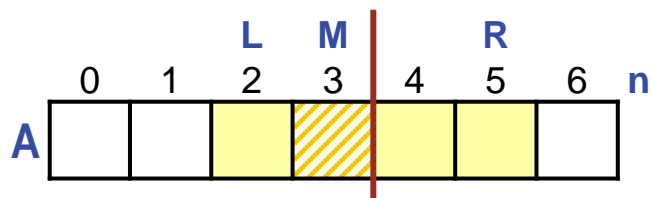
```
        R = _____ # Select left "half".
```

```
    else:
```

```
        L = _____ # Select right "half".
```

👉 Be alert to high-risk coding steps associated with binary choices.

Recognize that regions of even and odd lengths may need **distinct** treatments.



M is index of rightmost element of left “half”.

Application: Search for a value v in an ordered array $A[0..n-1]$.

```
# Given ordered array A[0..n-1],  $n \geq 0$ , and value  $v$ , let  $k$  be an index of A
# where  $A[k] == v$ , or  $n$  if there is no  $v$  in A.
```

```
L = _____; R = _____
```

```
M = (L + R) // 2 # Compute “midpoint”.
```

```
while _____:
```

```
    if _____:
```

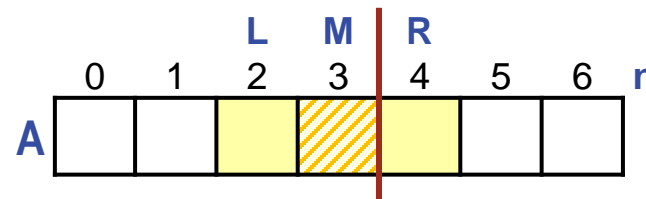
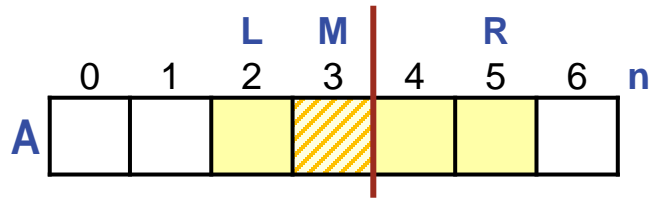
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        R = _____ # Select left “half”.
```

```
    else:
```

```
        L = _____ # Select right “half”.
```

👉 **Be alert to high-risk coding steps associated with binary choices.**

Recognize that regions of even and odd lengths may need **distinct** treatments, but **hope** for a **uniform** treatment.



M is index of rightmost element of left “half”.

Application: Search for a value v in an ordered array $A[0..n-1]$.

Given ordered array $A[0..n-1]$, $n \geq 0$, and value v , let k be an index of A
 # where $A[k]=v$, or n if there is no v in A .

$L = \underline{\hspace{2cm}}$; $R = \underline{\hspace{2cm}}$

$M = (L + R) // 2$ # Compute “midpoint”.

while $\underline{\hspace{2cm}}$:

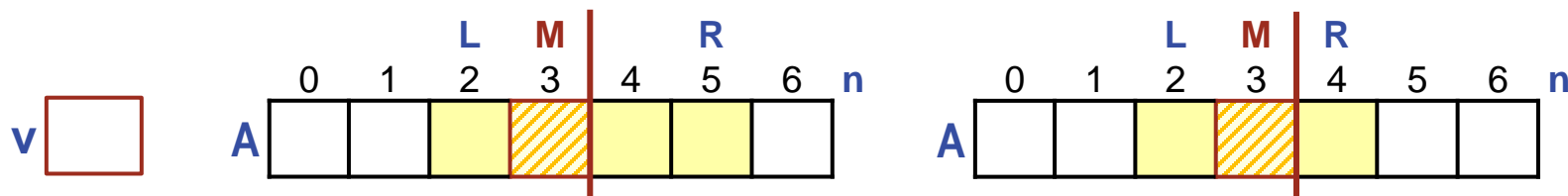
if $\underline{\hspace{2cm}}$:

$R = M$ # Select left “half”.

else:

$L = M + 1$ # Select right “half”.

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M is index of rightmost element of left “half”.

Application: Search for a value v in an ordered array $A[0..n-1]$.

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```

```
L = _____; R = _____
```

```
M = (L + R) // 2 # Compute “midpoint”.
```

```
while _____:
```

```
    if  $v \leq A[M]$ :
```

```
        R = M
```

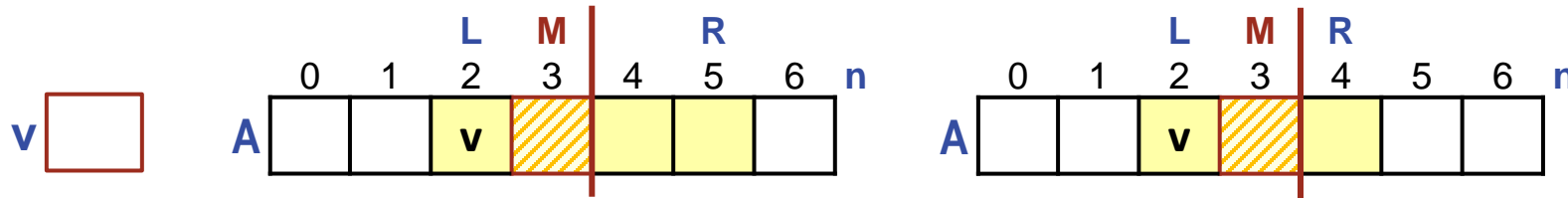
```
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```

```
    else:
```

```
        L = M + 1
```

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 **Be alert to high-risk coding steps associated with binary choices.**



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while _____:
```

```
    if  $v \leq A[M]$ :
```

```
        R = M
```

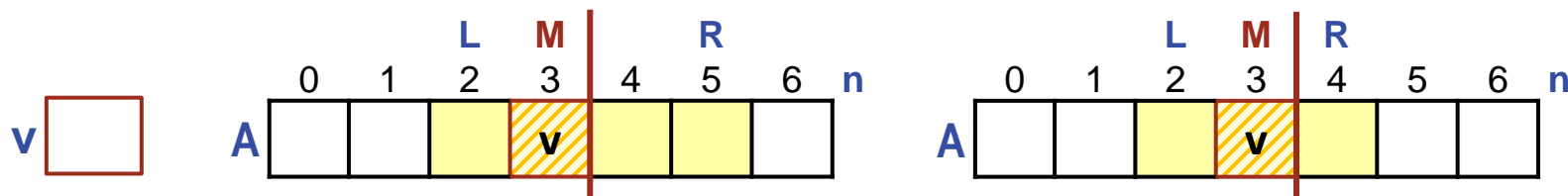
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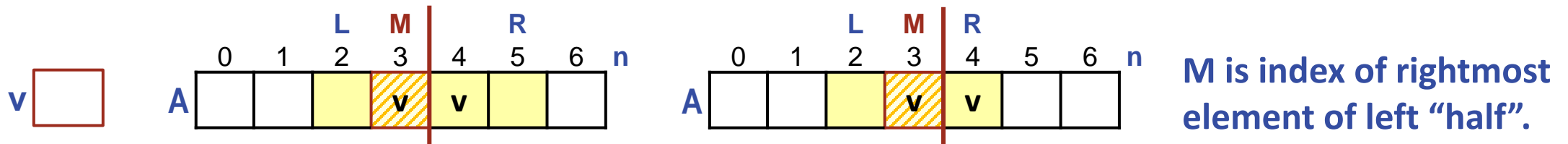
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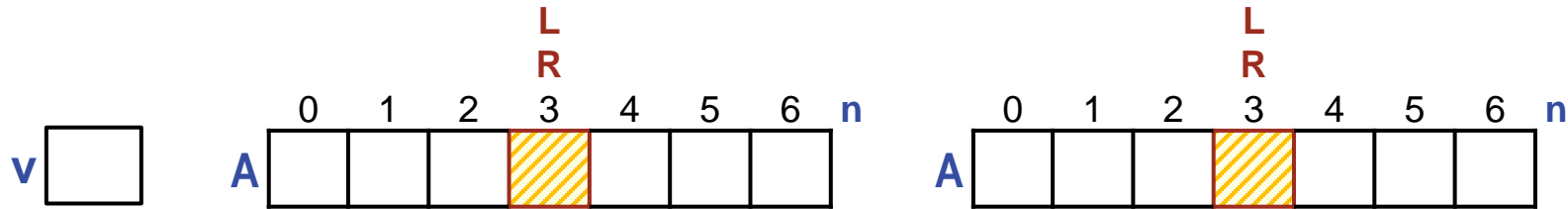
```
    else:
```

```
        L = M + 1
```

```
        # Select right “half”.
```

👉 Be alert to high-risk coding steps associated with binary choices.

Duplicate instances of v in $A[L..R]$ may escape, but not all of them.



Application: Search for a value v in an ordered array $A[0..n-1]$.

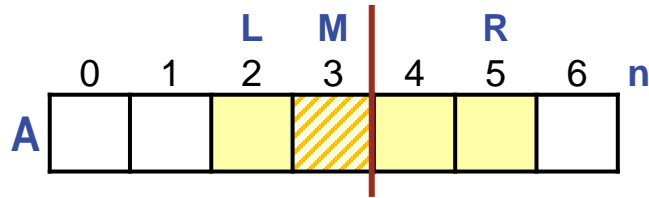
Given ordered array $A[0..n-1]$, $n \geq 0$, and value v , let k be an index of A
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$L = \underline{\hspace{2cm}}$; $R = \underline{\hspace{2cm}}$
 $M = (L + R) // 2$ # Compute "midpoint".

```

while L != R:
    if v <= A[M]:
        R = M           # Select left "half".
    else:
        L = M + 1      # Select right "half".
  
```

Coding order
(1) body
(2) termination
(3) initialization
(4) finalization
(5) boundary conditions



VARIANT:

Before			After (left)			After (right)		
L	R	R-L	L	R	R-L	L	R	R-L
2	5	3	2	3	1	4	5	1

Application: Search for a value v in an ordered array $A[0..n-1]$.

```
# Given ordered array A[0..n-1], n ≥ 0, and value v, let k be an index of A
# where A[k] == v, or n if there is no v in A.
```

```
L = _____; R = _____
```

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M = (L + R) // 2 # Compute "midpoint".
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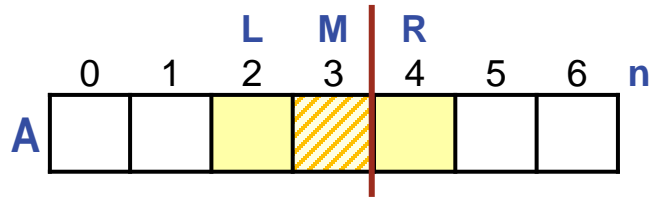
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        # Select right "half".
```

Coding order
(1) body
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Confirm that the **VARIANT** decreases on every iteration.



VARIANT:

Before			After (left)			After (right)		
L	R	R-L	L	R	R-L	L	R	R-L
2	4	2	2	3	1	4	4	0

Application: Search for a value v in an ordered array $A[0..n-1]$.

Given ordered array $A[0..n-1]$, $n \geq 0$, and value v , let k be an index of A
 # where $A[k] = v$, or n if there is no v in A .

$L = \underline{\hspace{2cm}}$; $R = \underline{\hspace{2cm}}$

$M = (L + R) // 2$ # Compute "midpoint".

while $L \neq R$:

if $v \leq A[M]$:

$R = M$

 # Select left "half".

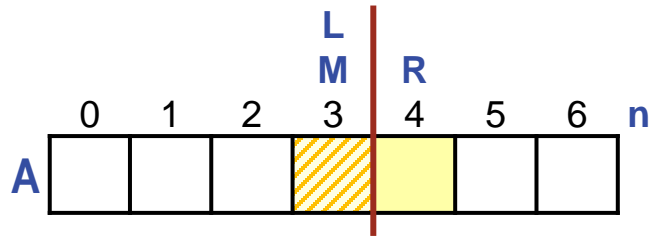
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$L = M + 1$

 # Select right "half".

Coding order
(1) body
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Confirm that the **VARIANT** decreases on every iteration.



VARIANT:

Before			After (left)			After (right)		
L	R	R-L	L	R	R-L	L	R	R-L
3	4	1	3	3	0	4	4	0

Application: Search for a value v in an ordered array $A[0..n-1]$.

Given ordered array $A[0..n-1]$, $n \geq 0$, and value v , let k be an index of A
 # where $A[k] == v$, or n if there is no v in A .

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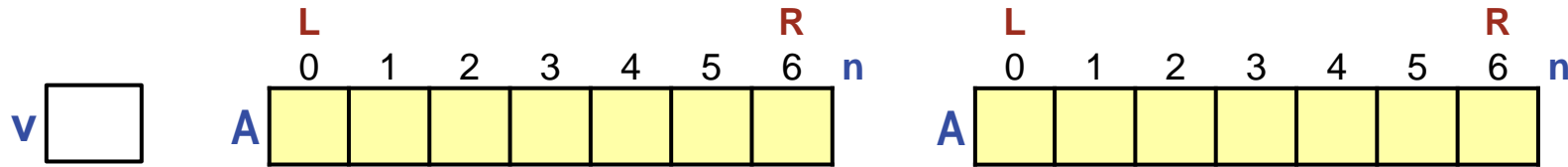
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Coding order
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Given ordered array $A[0..n-1]$, $n \geq 0$, and value v , let k be an index of A

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$L = 0$; $R = n - 1$

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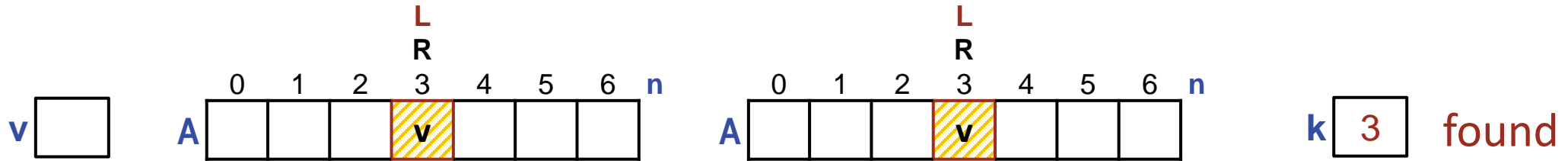
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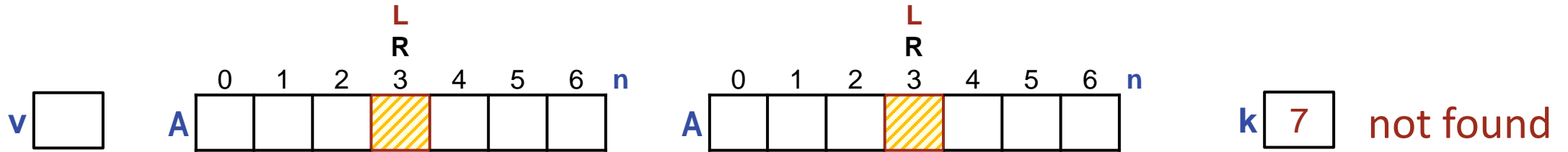
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Application: Search for a value v in an ordered array $A[0..n-1]$.

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# Given ordered array A[0..n-1], n ≥ 0, and value v, let k be an index of A
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L = 0; R = n - 1
M = (L + R) // 2      # Compute "midpoint".
while L != R:
    if v <= A[M]:
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if A[L] == v: k = L
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v A ^{$n=0$} k 0 not found

Application: Search for a value v in an ordered array $A[0..n-1]$.

Given ordered array $A[0..n-1]$, $n \geq 0$, and value v , let k be an index of A
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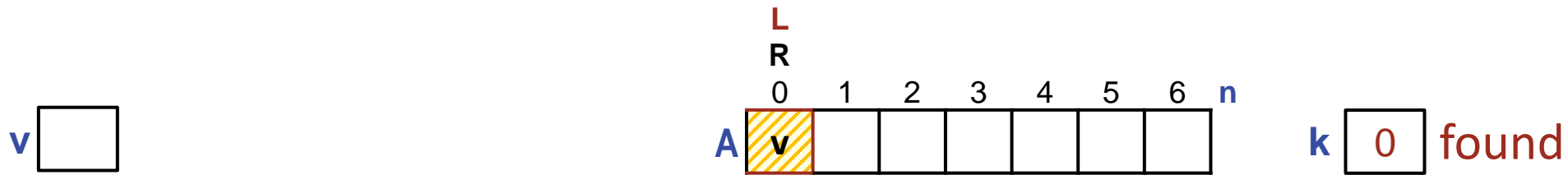
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$L = M + 1$ # Select right "half".

if $A[L] == v$: $k = L$

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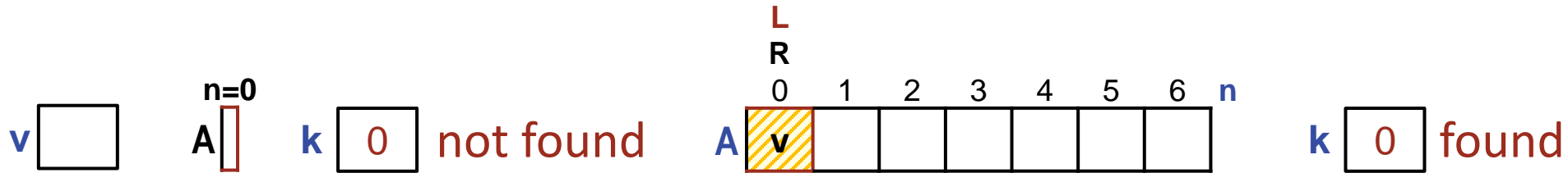
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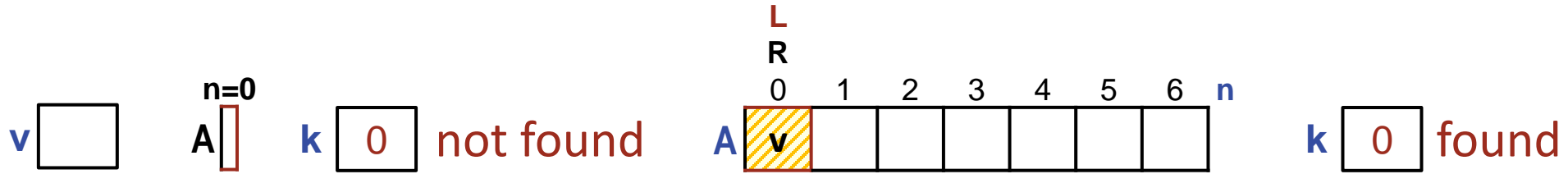
if $A[L] == v$: $k = L$

else: $k = n$

Coding order
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Is it a problem that $k=0$ represents both "not found" and "found in 0th element"?



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if $n == 0$: $k = 0$

else:

$L = 0$; $R = n - 1$

$M = (L + R) // 2$ # Compute "midpoint".

 while $L \neq R$:

 if $v \leq A[M]$:

$R = M$ # Select left "half".

 else:

$L = M + 1$ # Select right "half".

 if $A[L] == v$: $k = L$

 else: $k = n$

Coding order
(1) body
(2) termination
(3) initialization
(4) finalization
(5) boundary conditions

Test for found.
 if $k < n$: # Found.
 else: # Not found.



No. What matters is whether $k < n$, not whether $k == 0$.

Binary Search is astoundingly fast. If $n=512$, just 9 iterations to termination!

Iteration #	VARIANT
0	512
1	256
2	128
3	64
4	32
5	16
6	8
7	4
8	2
9	1

Running time is logarithmic in n ,
and independent of whether v is in A or not.