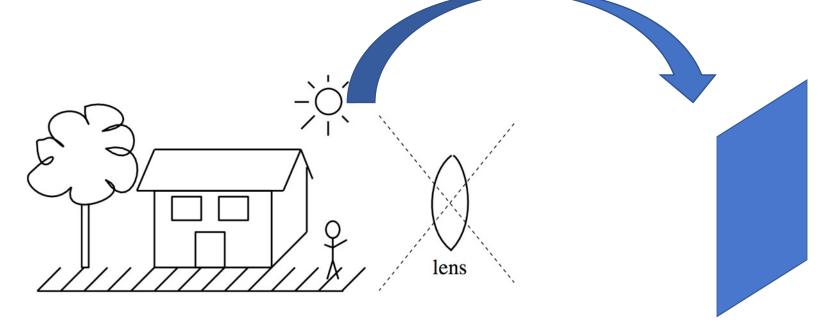
## Image Synthesis

## Why generative modeling?

- Understanding the visual world
- Generating samples for learning
- Unsupervised learning
- Graphics and image processing
- Art and creativity

## Synthesis for understanding - Analysis by synthesis

Hypothesize and generate



$$P(y \mid x) = \frac{P(x, y)}{P(x)}$$

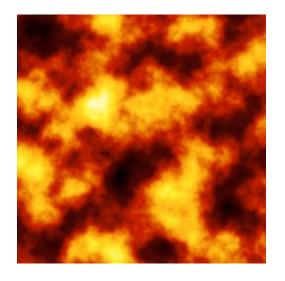
## Generating samples for learning



## Graphics and image processing



## We have been doing generation for a while...



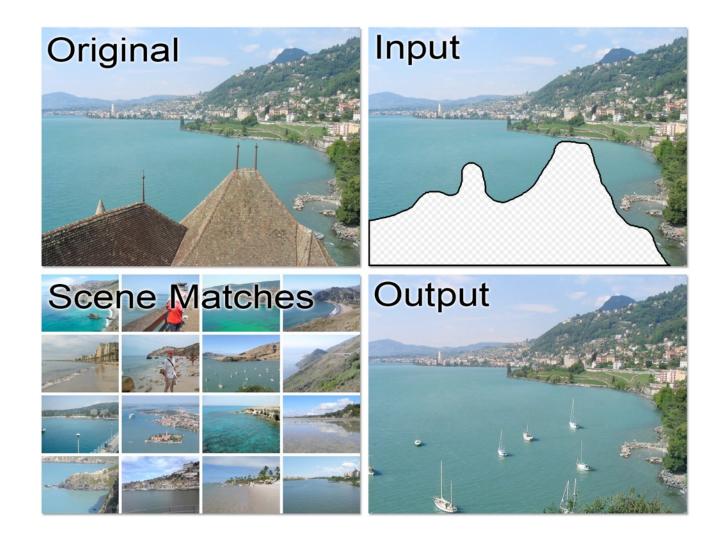
Perlin noise

## We have been doing generation for a while...





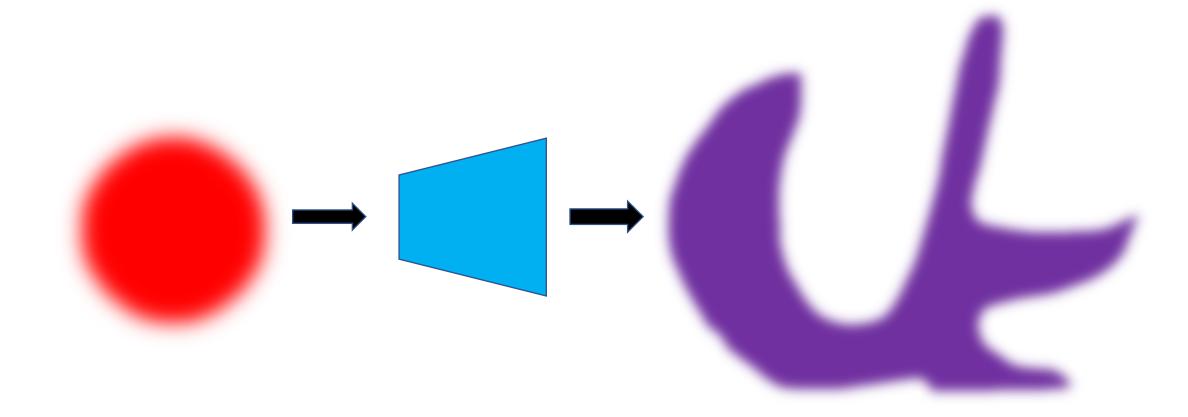
## We have been doing generation for a while...



### Learning generative models of images

- Standard probabilistic models (e.g. Gaussian)
  - Can be sampled from
  - Cannot capture arbitrary distributions
- Neural networks
  - Can learn to model arbitrary functions
  - Are deterministic
- Key idea 1: neural networks with noise input!

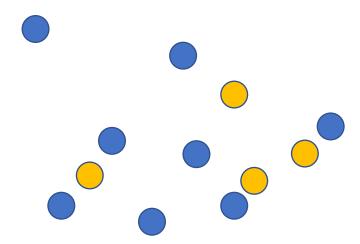
## Learning generative models of images



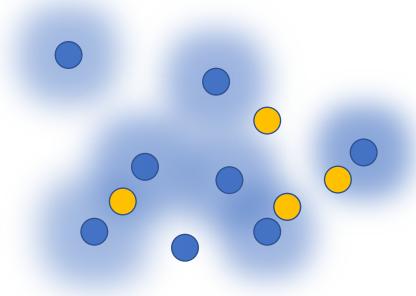
## Learning generative models of images

- Two distributions:  $p_{real}$  and  $p_{model}$
- Both highly multimodal, high-dimensional
- Only have samples from each distribution
- Want to minimize the difference between the two distributions

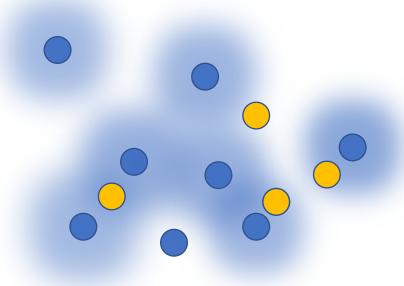
• Idea 1: parzen window estimation



- Idea 1: parzen window estimation
- Plop a Gaussian at each sample to convert samples into a distribution



- Idea 1: parzen window estimation
- Problem: calculating distances an issue in high dimensional spaces
- Need dense sampling



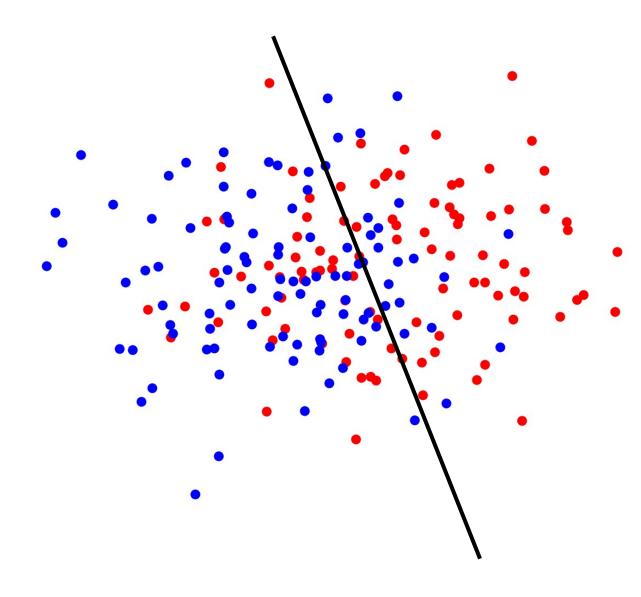
- Idea 1: parzen window estimation
- Problem: calculating distances an issue in high dimensional spaces
- Need dense sampling





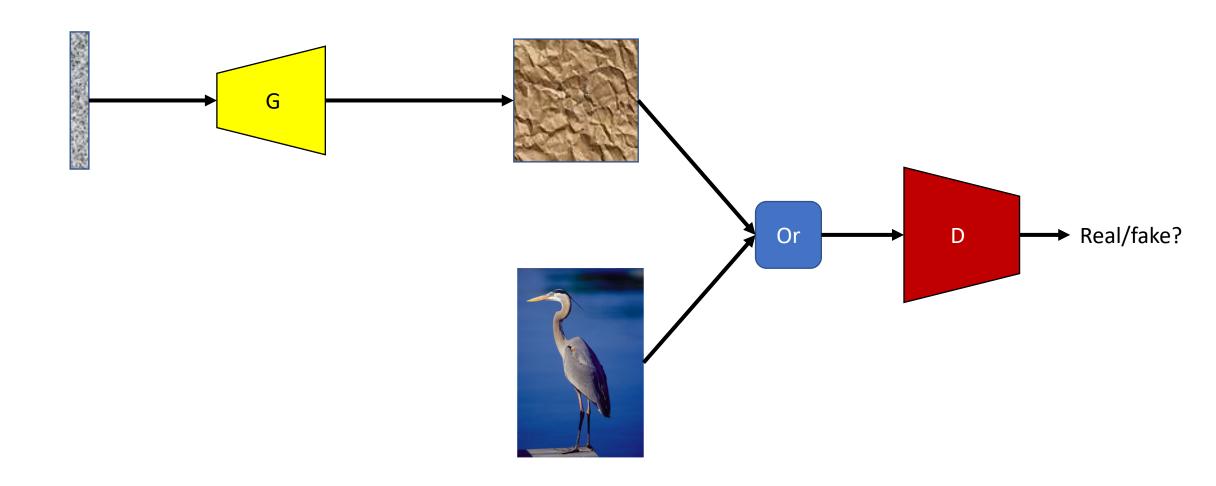
## The adversary

• Train a classifier to see if the distributions are different!



## The adversary

- Essentially the same idea as:
  - Maximum mean discrepancy (MMD)
  - A-distance



- Perspective 1: Two player game
  - Discriminator's job to distinguish model samples from real thing
  - Generator's job to fool the discriminator
- Perspective 2: Density estimation

$$D(x) = \frac{p_{data}(x)}{p_{model}(x) + p_{data}(x)}$$

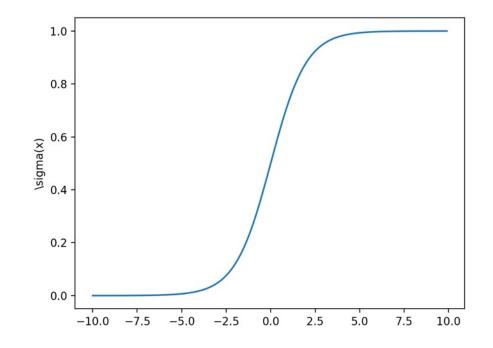
- Discriminator estimates density and tells generator which samples are unlikely
- Generator learns to sample

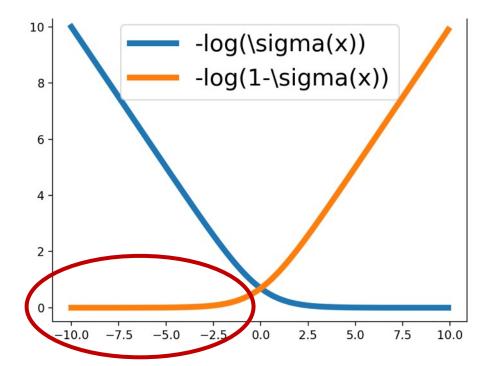
$$\max_{G} \min_{D} (-\mathbb{E}_x \log D(x) - \mathbb{E}_z \log(1 - D(G(z))))$$

- Training:
- Sample x
- Sample z
- Take step(s) along discriminator
- Take step(s) along generator

$$\max_{G} \min_{D} (-\mathbb{E}_x \log D(x) - \mathbb{E}_z \log(1 - D(G(z))))$$

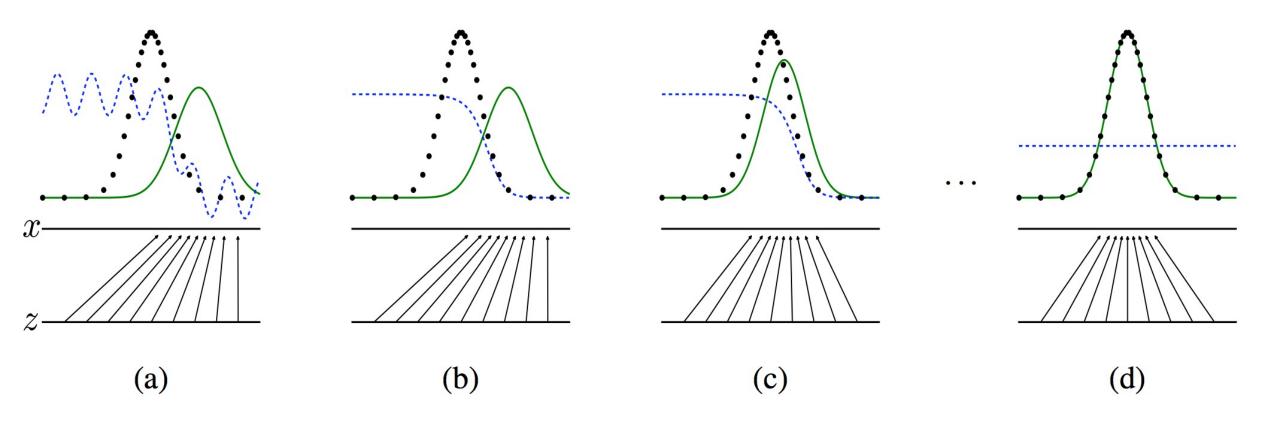
- Usually, discriminator's task is easier
- D(G(z)) often close to 0



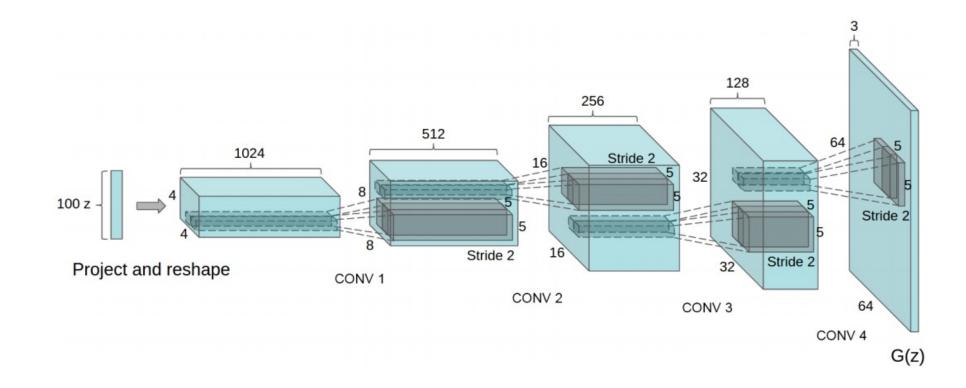


$$J_D(x) = -\mathbb{E}_x \log D(x) - \mathbb{E}_z \log(1 - D(G(z)))$$
$$J_G(x) = -\mathbb{E}_z \log D(G(z))$$

## Generative Adversarial Networks (GANs)



#### Generative adversarial networks



Radford, Alec, Luke Metz, and Soumith Chintala. "Unsupervised representation learning with deep convolutional generative adversarial networks." *arXiv preprint arXiv:1511.06434* (2015).

## What do GANs generate?



Radford, Alec, Luke Metz, and Soumith Chintala. "Unsupervised representation learning with deep convolutional generative adversarial networks." *arXiv preprint arXiv:1511.06434* (2015).

#### **GAN** variants

#### Real-valued discriminator

#### **Gradient penalty**

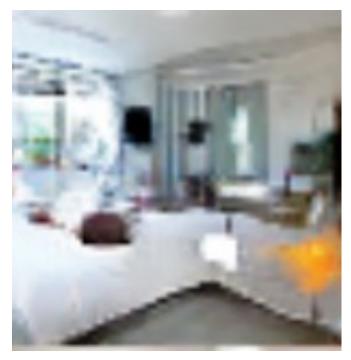
Table 1: Generator and discriminator loss functions. The main difference whether the discriminator outputs a probability (MM GAN, NS GAN, DRAGAN) or its output is unbounded (WGAN, WGAY GP, LS GAN, BEGAN), whether the gradient penalty is present (WGAN GP, DRAGAN) and where is it evaluated. We chose those mode's based on their popularity.

GAN	DISCRIMINATOR LOSS		GENERATOR LOSS
MM GAN	$\mathcal{L}_{ extsf{D}}^{ ext{GAN}} = -\mathbb{E}_{x \sim p_d}[\log(D(x))]$ .	$-\mathbb{E}_{\hat{x} \sim p_g}[\log(1 - D(\hat{x}))]$	$\mathcal{L}_{ ext{G}}^{ ext{GAN}} = \mathbb{E}_{\hat{x} \sim p_g}[\log(1 - D(\hat{x}))]$
NS GAN	$\mathcal{L}_{ extsf{D}}^{ extsf{NSGAN}} = -\mathbb{E}_{x \sim p_d}[\log(D(x))]$	$[-\mathbb{E}_{\hat{x} \sim p_g}[\log(1 - D(\hat{x}))]$	$\mathcal{L}_{ ext{G}}^{ ext{ iny NSGAN}} = -\mathbb{E}_{\hat{x} \sim p_{m{g}}}[\log(D(\hat{x}))]$
WGAN	$\mathcal{L}_{ extsf{D}}^{ ext{WGAN}} = -\mathbb{E}_{x \sim p_d}[D(x)] + \mathbb{E}_{x \sim p_d}[D(x)]$	$\hat{x} \sim p_g [D(\hat{x})]$	$\mathcal{L}_{ ext{G}}^{ ext{ iny WGAN}} = -\mathbb{E}_{\hat{x} \sim p_g}[D(\hat{x})]$
WGAN GP	$\mathcal{L}_{ extsf{D}}^{ ext{wgangp}} = \mathcal{L}_{ extsf{D}}^{ ext{wgan}} + \lambda \mathbb{E}_{\hat{x} \sim p_g}[$	$(  \nabla D(\alpha x + (1 - \alpha \hat{x})  _{\mathcal{T}} - 1)^2]$	$\mathcal{L}_{ ext{G}}^{ ext{wgangp}} = -\mathbb{E}_{\hat{x} \sim p_g}[D(\hat{x})]$
LS GAN	$\mathcal{L}_{ extsf{D}}^{ extsf{LSGAN}} = -\mathbb{E}_{x \sim p_d}[(D(x) - 1$	$[D(\hat{x})^2] + \mathbb{E}_{\hat{x} \sim p_g} [D(\hat{x})^2]$	$\mathcal{L}_{ ext{G}}^{ ext{ iny LSGAN}} = -\mathbb{E}_{\hat{x} \sim p_g}[(D(\hat{x}-1)^2]$
DRAGAN	$\mathcal{L}_{ extsf{D}}^{ extsf{D} extsf{RAGAN}} = \mathcal{L}_{ extsf{D}}^{ extsf{GAN}} + \lambda \mathbb{E}_{\hat{x} \sim p_d} + \lambda \mathcal{E}_{\hat{x}}$	$\chi_{(0,c)}[(  \nabla D(\hat{x})  _2-1)^2]$	$\mathcal{L}_{ ext{G}}^{ ext{dragan}} = \mathbb{E}_{\hat{x} \sim p_g}[\log(1 - D(\hat{x}))]$
BEGAN	$\mathcal{L}_{ extsf{D}}^{ ext{BEGAN}} = \mathbb{E}_{x \sim p_d}[  x -  ext{AE}(x) ]$	$   _1] - k_t \mathbb{E}_{\hat{x} \sim p_g}[  \hat{x} - AE(\hat{x})  _1]$	$\mathcal{L}_{ ext{G}}^{ ext{BEGAN}} = \mathbb{E}_{\hat{x} \sim p_g}[  \hat{x} -  ext{AE}(\hat{x})  _1]$

Lucic, Mario, et al. "Are gans created equal? a large-scale study." *arXiv preprint arXiv:1711.10337*(2017).

## What do GANs generate?

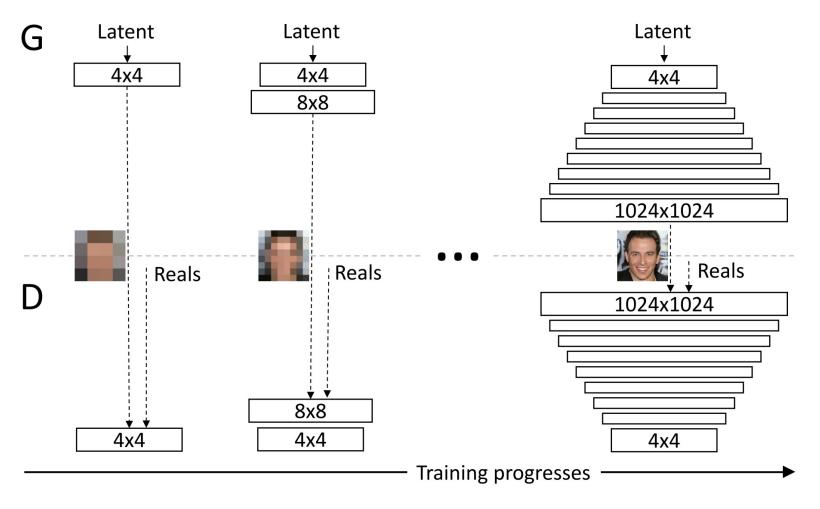






Radford, Alec, Luke Metz, and Soumith Chintala. "Unsupervised representation learning with deep convolutional generative adversarial networks." *arXiv preprint arXiv:1511.06434* (2015).

## What do GANs generate?



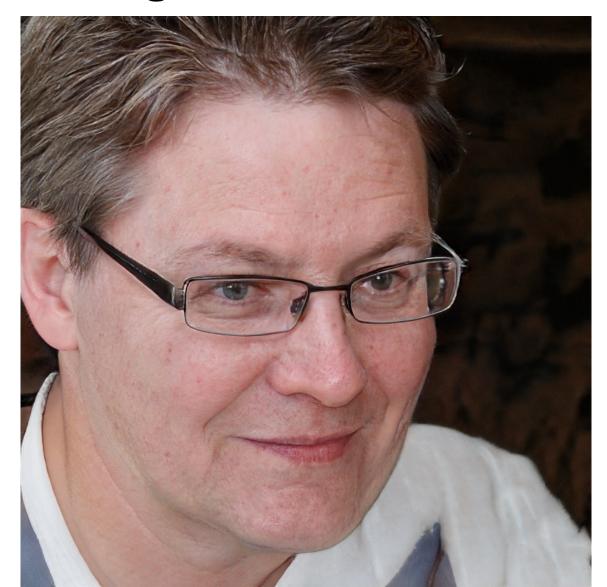


## New generation architectures

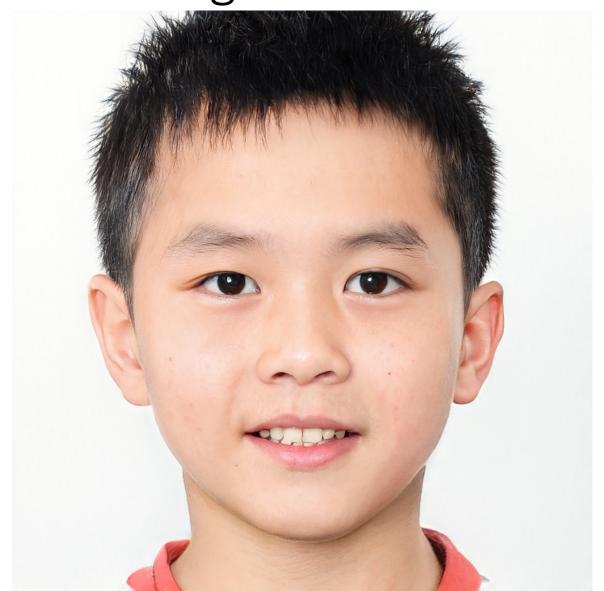
Latent  $\mathbf{z} \in \mathcal{Z}$ Latent  $\mathbf{z} \in \mathcal{Z}$ Noise Synthesis network gNormalize Normalize Const 4×4×512 Mapping B network f Fully-connected AdaIN PixelNorm Conv 3×3 **B** ← Conv 3×3 FC style AdaIN FC PixelNorm FC 4×4 Upsample Upsample FC Conv 3×3 Conv 3×3 FC **B** ← PixelNorm AdaIN Conv 3×3 Conv 3×3 **B** ←  $\mathbf{w} \in \mathcal{W}$ PixelNorm 8×8 8×8 (a) Traditional (b) Style-based generator

Karras, Tero, Samuli Laine, and Timo Aila. "A style-based generator architecture for generative adversarial networks." *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*. 2019.

## State-of-the-art generation



State-of-the-art generation



## State-of-the-art generation



#### Some caveats about faces

• Faces are *almost* linear



Original face

Reconstruction from 7 principal components

## PCA components of faces

- First few basis elements: shading
- Next basis elements: identity + expression



Basis images 1-4 model the shading

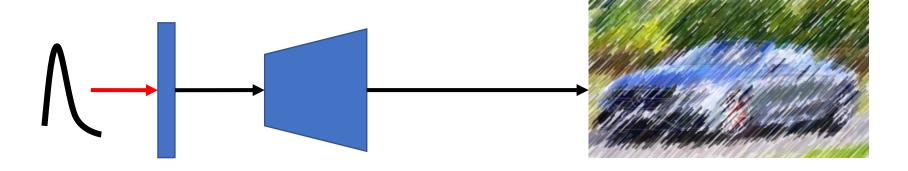
Rest of the basis images (five representatives are shown) model the facial expression

https://grail.cs.washington.edu/cflow/

## Variational Autoencoders

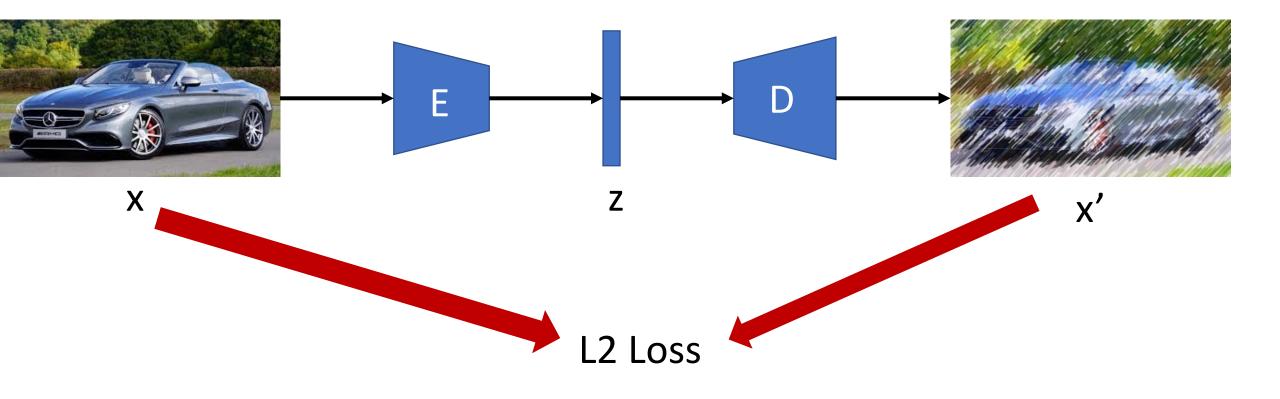
### Back to generative models

- Need a probabilistic model we can sample from
- · Write probabilistic model so that training images are highly likely
  - Probabilistic model maps noise from standard Gaussian to image
  - But which noise generates which training image?

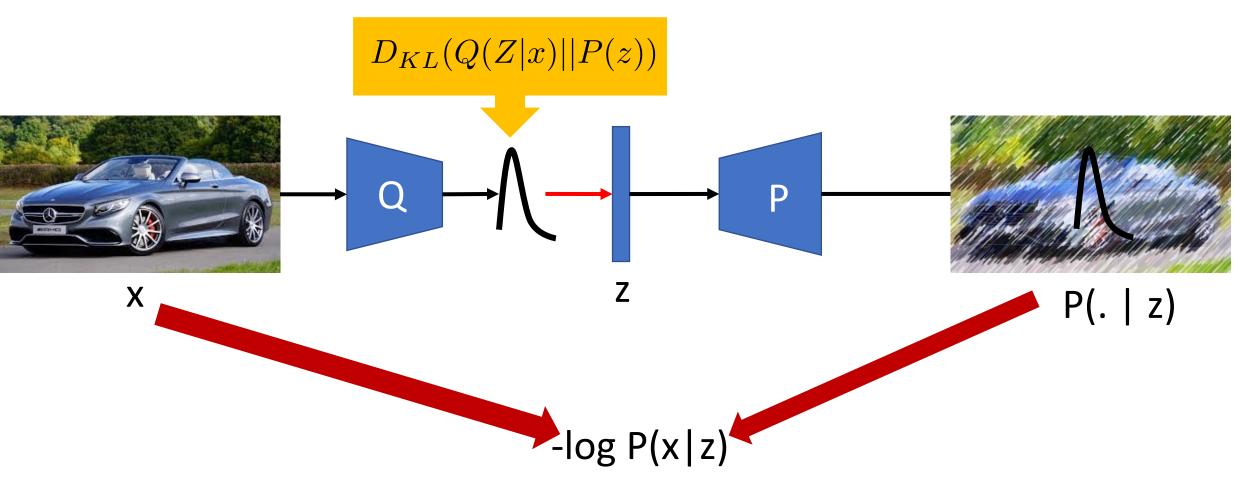


#### Autoencoders

- Maps each image to a particular latent code
- But not a probabilistic model!



#### Variational autoencoders



Tutorial on Variational Autoencoders. Carl Doersch. https://arxiv.org/pdf/1606.05908.pdf