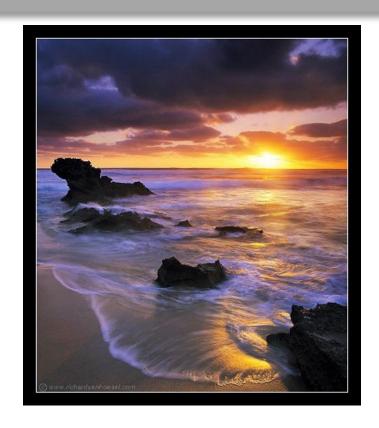
CS5670: Computer Vision

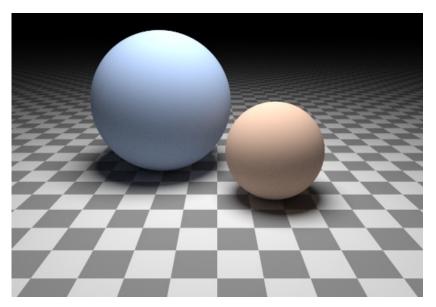
Light & Perception



Reading

• Szeliski 2nd Edition, Chapter 2.2

Can we determine shape from *lighting*?



- Are these spheres?
 - Or just flat discs painted with varying color (albedo)?
 - There is ambiguity between *shading* and *reflectance*
 - But still, as humans we can understand the shapes of these

What we know: Stereo







Key Idea: use camera motion to compute shape

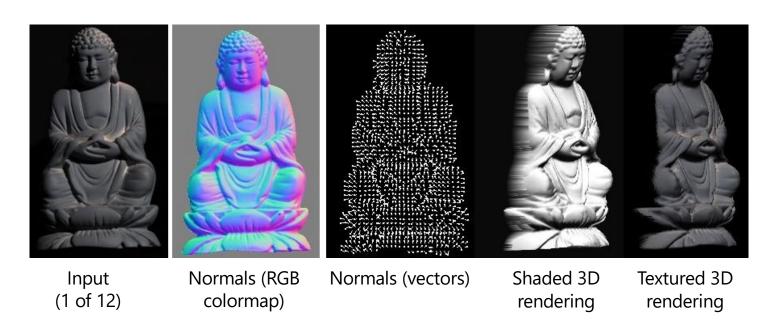
Next: Photometric Stereo

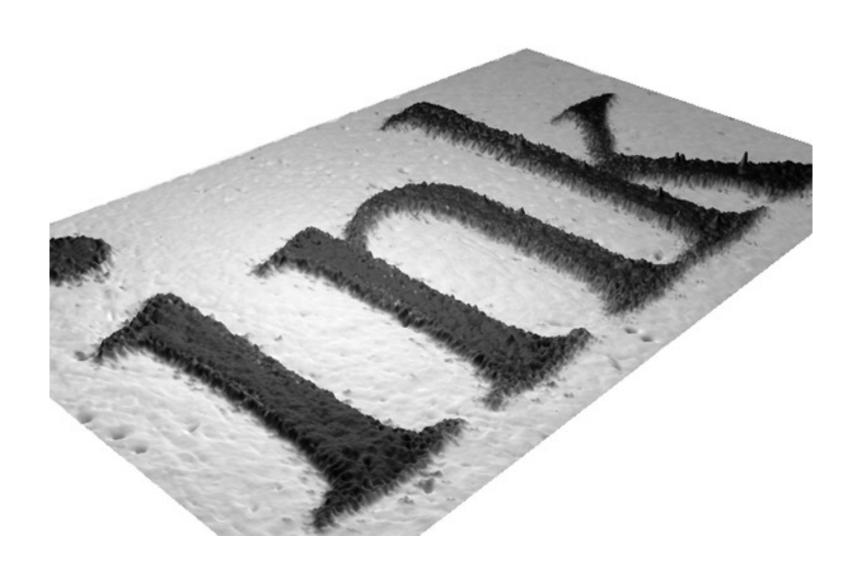


Key Idea: use pixel brightness to understand shape

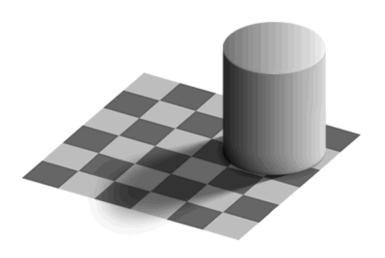
Photometric Stereo

What results can you get?





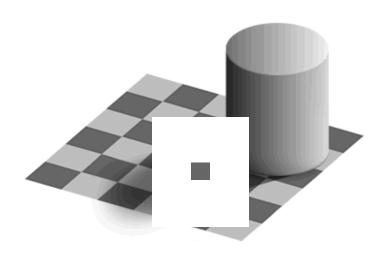
Light



by Ted Adelson

- Readings
 - Szeliski, 2.2, 2.3

Light



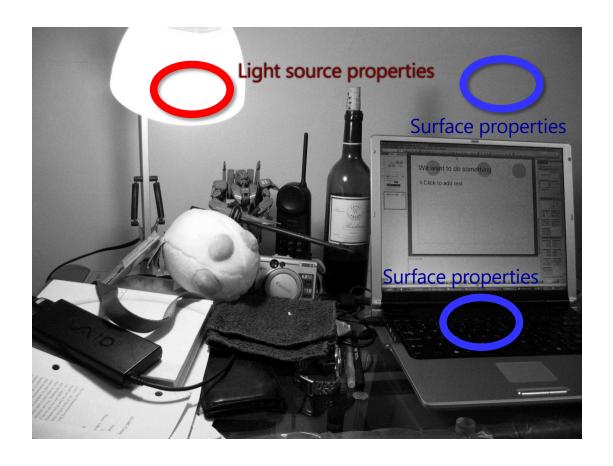
by Ted Adelson

- Readings
 - Szeliski, 2.2, 2.3

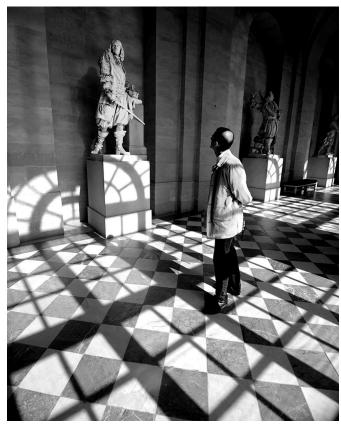
Properties of light

- Today
 - What is light?
 - How do we measure it?
 - How does light propagate?
 - How does light interact with matter?

• What determines the brightness of a pixel?



• What determines the brightness of a pixel?



<u>@robertwestonbreshears</u> https://www.instagram.com/p/BtgX55ZBhU-/

• What determines the brightness of a pixel?



• What determines the brightness of a pixel?

Sensor characteristics

Exposure

Surface shape

Surface reflectance

Optics

properties

Slide by L. Fei-Fei

Color perception

Electromagnetic radiation (EMR) moving along rays in space

- $R(\lambda)$ is EMR, measured in units of power (watts)
 - $-\lambda$ is wavelength

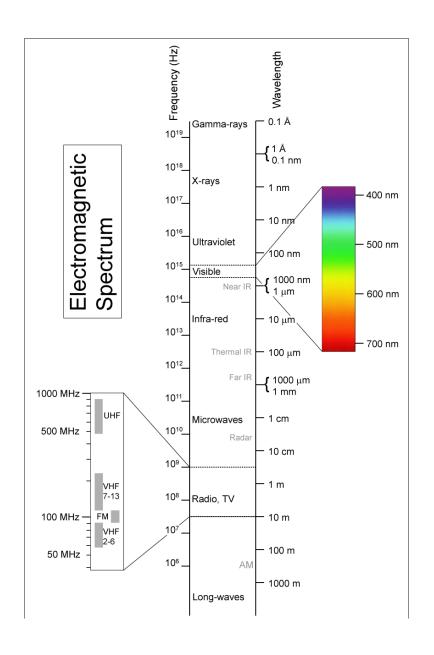


Perceiving light

- How do we convert radiation into "color"?
- What part of the spectrum do we see?

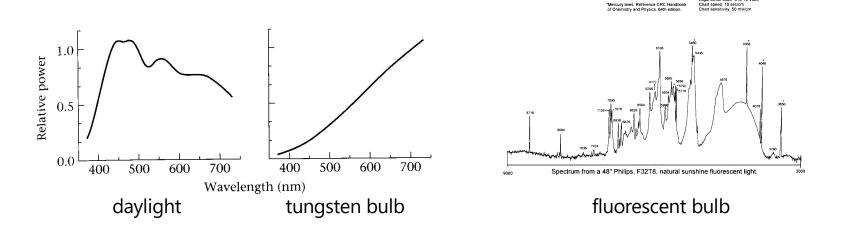
Visible light

We "see" electromagnetic radiation in a range of wavelengths



Light spectrum

- The appearance of light depends on its power **spectrum**
 - How much power (or energy) at each wavelength

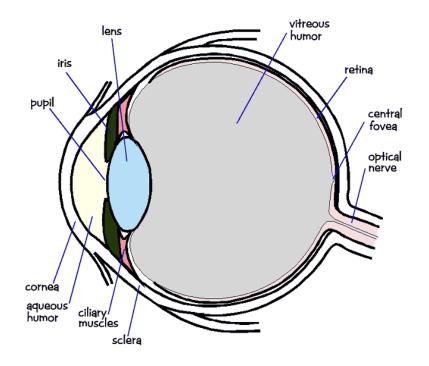


Our visual system converts a light spectrum into "color"

• This is a rather complex transformation

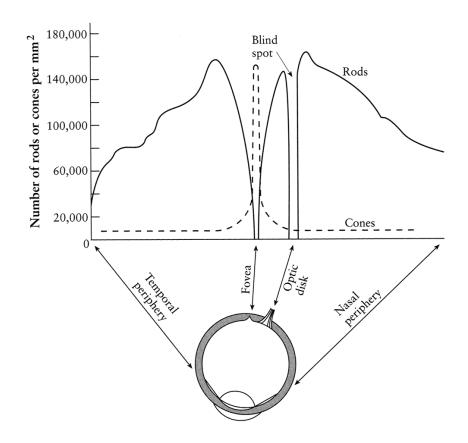
The human visual system

- Color perception
 - Light hits the retina, which contains photosensitive cells
 - rods and cones
 - These cells convert the spectrum into a few discrete values



Density of rods and cones

- Rods and cones are non-uniformly distributed on the retina
 - Rods responsible for intensity, cones responsible for color
 - Fovea: Small region (1 or 2°) at the center of the visual field containing the highest density of cones (and no rods).
 - Less visual acuity in the periphery—many rods wired to the same neuron



Demonstrations of visual acuity



With one eye shut, at the right distance, all of these letters should appear equally legible (Glassner, 1.7).

Demonstrations of visual acuity

With left eye shut, look at the cross on the left. At the right distance, the circle on the right should disappear (Glassner, 1.8).

Brightness contrast and constancy

- The apparent brightness depends on the surrounding region
 - brightness contrast: a constant colored region seems lighter or darker depending on the surrounding intensity



 brightness constancy: a surface looks the same under widely varying lighting conditions.

Light response is nonlinear

- Our visual system has a large dynamic range
 - We can resolve both light and dark things at the same time
 - One mechanism for achieving this is that we sense light intensity on a logarithmic scale
 - an exponential intensity ramp will be seen as a linear ramp
 - Another mechanism is adaptation
 - rods and cones adapt to be more sensitive in low light, less sensitive in bright light.

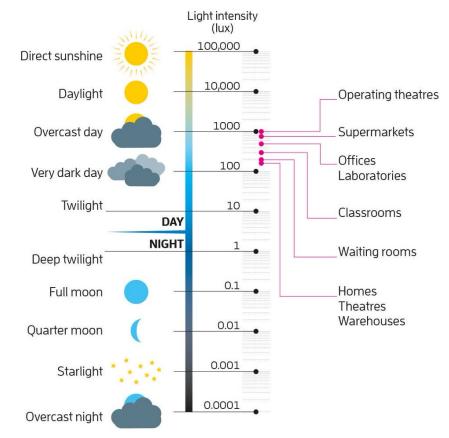
Visual dynamic range

A piece of white paper can be 1,000,000,000 times brighter in outdoor sunlight than in a moonless night.

BUT in a given lighting condition, light perception ranges over only about two orders of magnitude.

The light in our lives

Even the brightest indoor spaces are dim compared with the outdoors in daylight



SOURCE: NATIONAL OPTICAL ASTRONOMY OBSERVATORY

https://threader.app/thread/1134003178515701762

Learning to See in the Dark

Chen Chen, Qifeng Chen, Jia Xu and Vladlen Koltun

IEEE Conference on Computer Vision and Pattern Recognition (CVPR), 2018

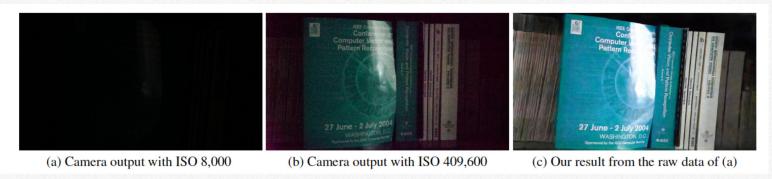


Figure. Extreme low-light imaging by a Sony a7S II camera using ISO 8000, f/5.6, 1/30 second. Dark indoor environment. The illuminance at the camera is <0.1 lux.

http://cchen156.web.engr.illinois.edu/SID.html

Dancing under the stars: video denoising in starlight

CVPR 2022

Kristina Monakhova
UC Berkeley

Stephan Richter Intel Labs Laura Waller UC Berkeley

Vladlen Koltun Intel Labs

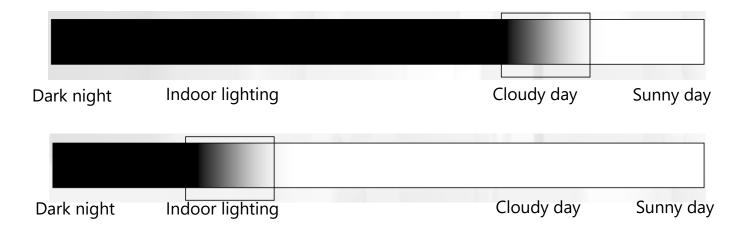


Visual dynamic range



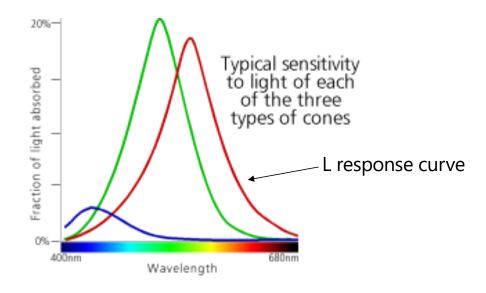
If we were sensitive to this whole range all the time, we wouldn't be able to discriminate lightness levels in a typical scene.

The visual system solves this problem by restricting the 'dynamic range' of its response to match the current overall or 'ambient' light level.

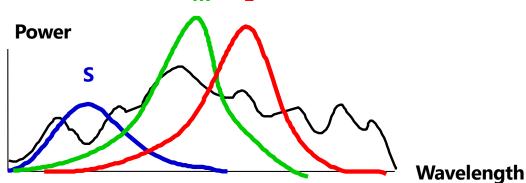


Color perception

- Three types of cones
 - Each is sensitive in a different region of the spectrum
 - but regions overlap
 - Short (S) corresponds to blue
 - Medium (M) corresponds to green
 - Long (L) corresponds to red
 - Different sensitivities: we are more sensitive to green than red
 - varies from person to person (and with age)
 - Colorblindness—deficiency in at least one type of cone

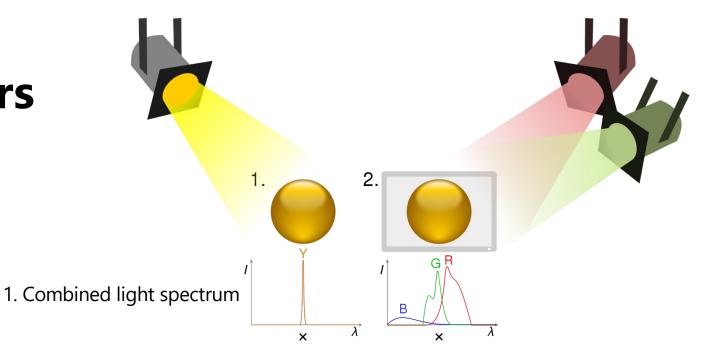


Color perception

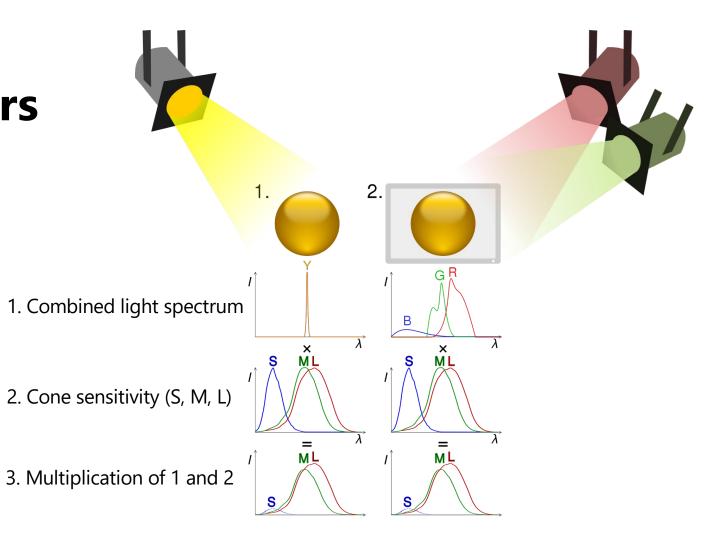


- Rods and cones act as filters on the spectrum
 - To get the output of a filter, multiply its response curve by the spectrum, integrate over all wavelengths
 - Each cone yields one number
 - Q: How can we represent an entire spectrum with 3 numbers?
 - A: We can't! Most of the information is lost
 - As a result, two different spectra may appear indistinguishable
 - such spectra are known as metamers

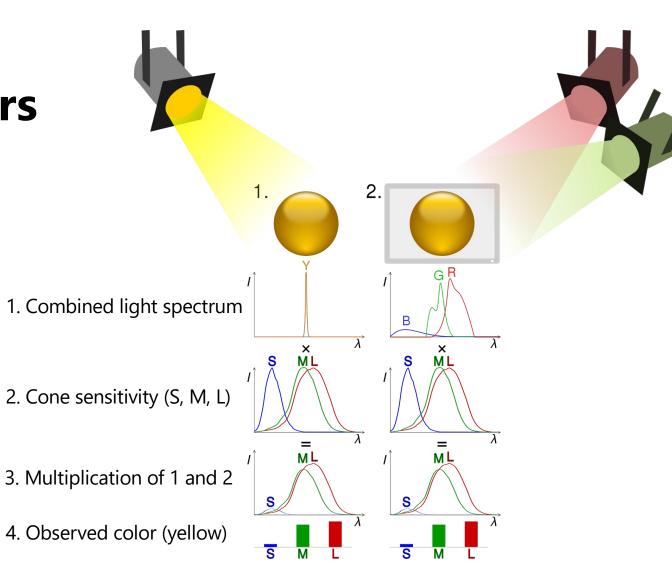
Metamers



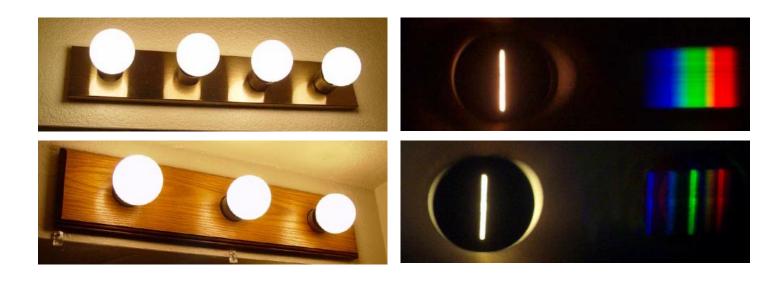
Metamers



Metamers



What kind of bulb is it?



http://www.chemistryland.com/CHM107Lab/Exp7/Spectroscope/Spectroscope.html

What color is the dress?

- White and gold?
- Black and blue?



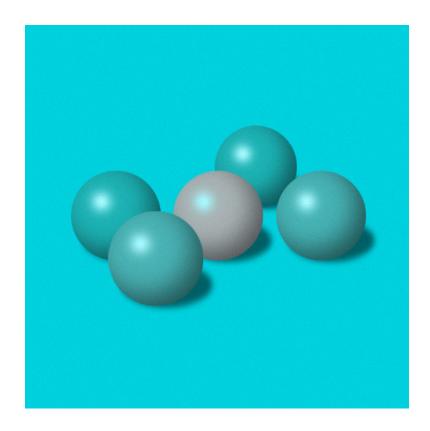
slido



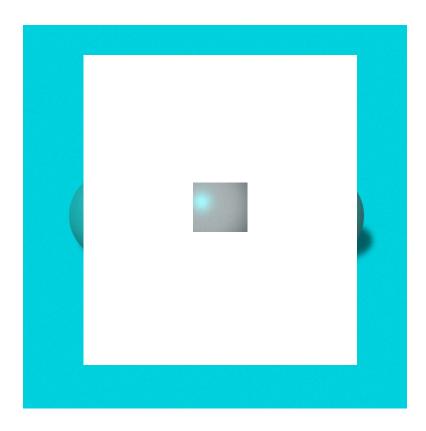
What color is the dress?

① Start presenting to display the poll results on this slide.

What color is the center ball?

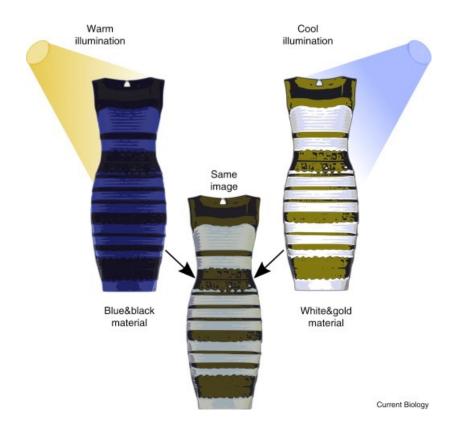


What color is the center ball?



Reflectance and Illumination In Popular Culture...





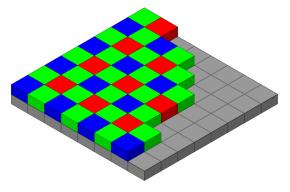
Perception summary

- The mapping from radiance to perceived color is quite complex!
 - We throw away most of the data
 - We apply a logarithm
 - Brightness affected by pupil size and adaptation of rods/cones
 - Brightness contrast and constancy effects

- The same is true for cameras
 - But we have tools to correct for these effects
 - (Computational Photography)

Cameras also see color

 Common technique is to place a mosaic of color filters (a *Bayer filter*) in front of the sensor



Bayer filter pattern in front of sensor

 Colors are interpolated to create a full-resolution "demosaicked" color image



What the camera sees ("raw" image)



Demosaicked image

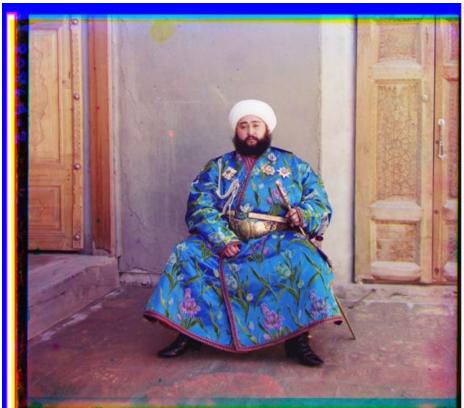
https://en.wikipedia.org/wiki/Bayer_filter

Early color photography

 Prior to the invention of color film, Sergey Prokudin-Gorsky took three separate exposures with three different color filters



Blue, Green, Red exposures



Combined color image (1911)

Film has its own sensitivity

 "... the film of Lincoln's era was sensitive only to blue and UV light, causing cheeks to appear dark, and overly emphasizing wrinkles by filtering out skin subsurface scatter which occurs mostly in the red channel. Hence, the deep lines and sharp creases that we associate with Lincoln's face are likely exaggerated by the photographic process of the

<u>Time-Travel Replectography</u>

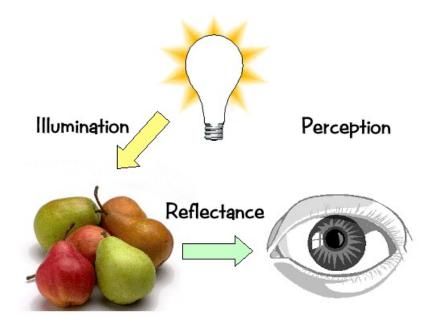
<u>Xuan Luo, Xuaner Zhang, Paul Yoo, Ricardo Martin-Brualla, Jason Lawrence, Steven M. Seitz</u>

SIGGRAPH Asia 2021



Questions?

Light transport



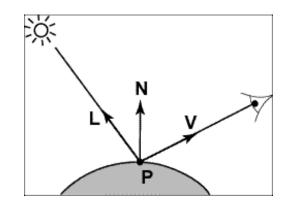
Light sources

- Basic types
 - point source
 - directional source
 - a point source that is infinitely far away
 - area source
 - a union of point sources
- More generally
 - a light field can describe *any* distribution of light sources
- What happens when light hits an object?

Modeling Image Formation

We need to reason about:

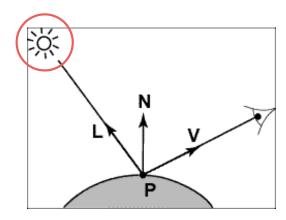
- How light interacts with the scene
- How a pixel value is related to light energy in the world



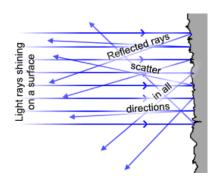
Track a "ray" of light all the way from light source to the sensor

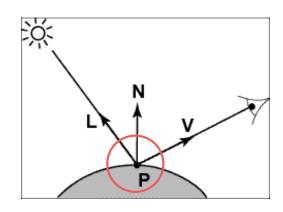
Directional Lighting

- Key property: all rays are parallel
- Equivalent to an infinitely distant point source



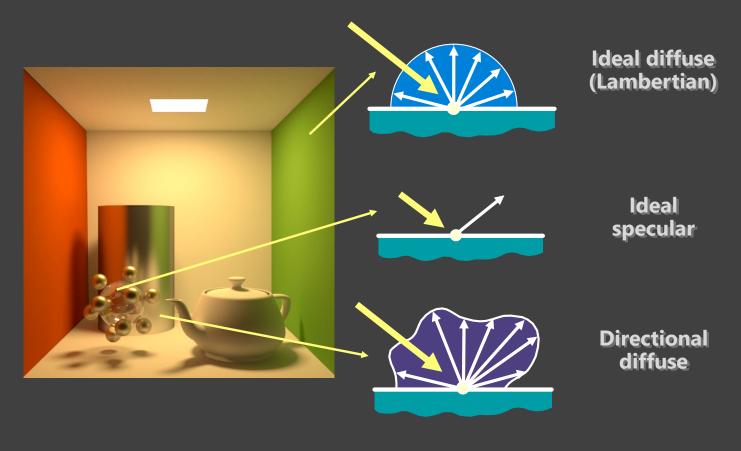
Lambertian Reflectance



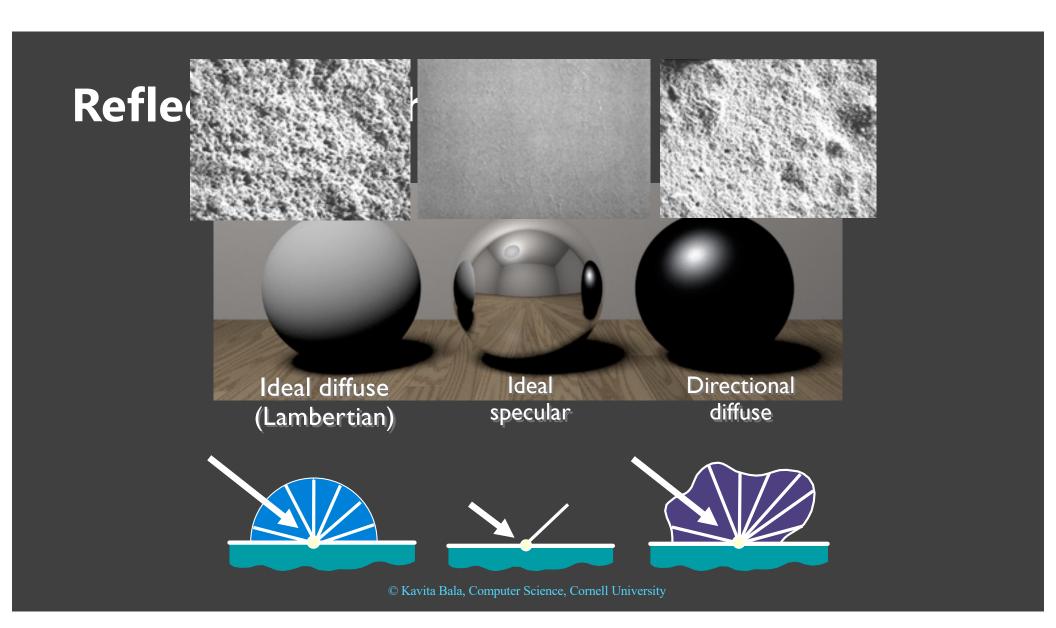


$$I = N \cdot L$$
 Image Surface Light intensity normal direction Image intensity $\propto \cos(\text{angle between N and L})$

Materials - Three Forms

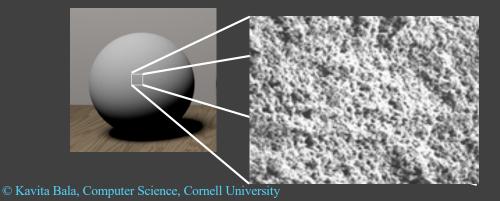


© Kavita Bala, Computer Science, Cornell University

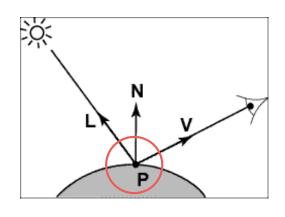


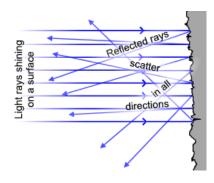
Ideal Diffuse Reflection

- Characteristic of multiple scattering materials
- An idealization but reasonable for matte surfaces



Lambertian Reflectance

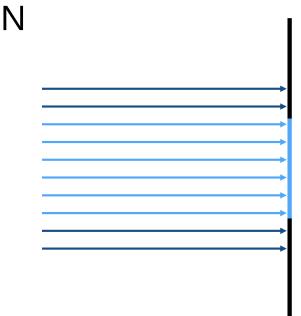




- 1. Reflected energy is proportional to cosine of angle between L and N (incoming)
- 2. Measured intensity is viewpoint-independent (outgoing)

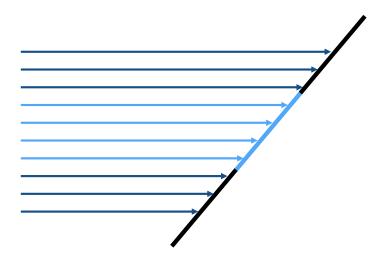
Lambertian Reflectance: Incoming

 Reflected energy is proportional to cosine of angle between L and N



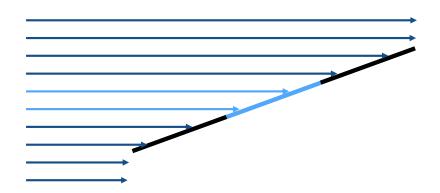
Lambertian Reflectance: Incoming

 Reflected energy is proportional to cosine of angle between L and N



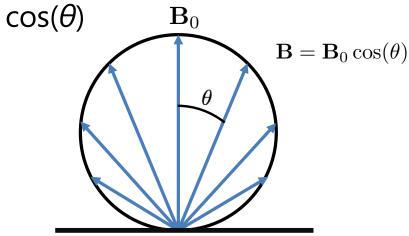
Lambertian Reflectance: Incoming

 Reflected energy is proportional to cosine of angle between L and N



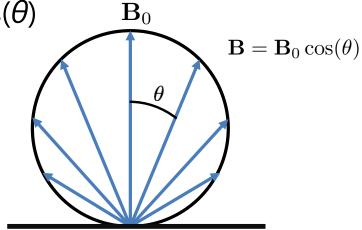
Light hitting surface is proportional to the **cosine**

• Number of photons reflected to a given angle θ is proportional to



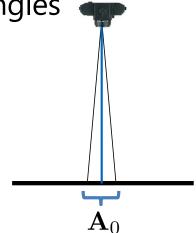
Lambert's cosine law: $\mathbf{B} = \mathbf{B}_0 \cos(\theta)$

• Number of photons reflected to a given angle θ is proportional to $\cos(\theta)$ \mathbf{B}_0

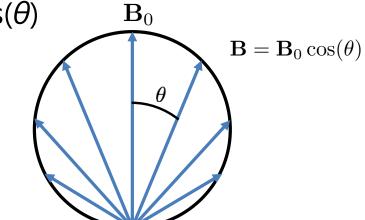


Lambert's cosine law: $\mathbf{B} = \mathbf{B}_0 \cos(\theta)$

 But appearance is the same from every angle due to larger pixel footprint at larger angles

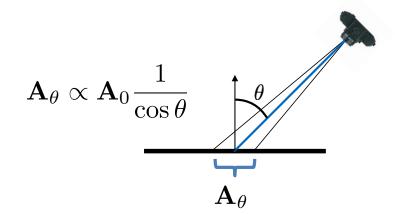


• Number of photons reflected to a given angle θ is proportional to $\cos(\theta)$ \mathbf{B}_0

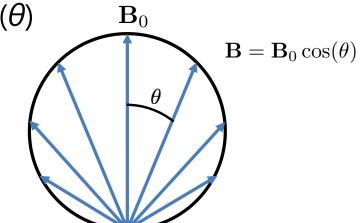


Lambert's cosine law: $\mathbf{B} = \mathbf{B}_0 \cos(\theta)$

 But appearance is the same from every angle due to larger pixel footprint at larger angles



• Number of photons reflected to a given angle θ is proportional to $\cos(\theta)$ \mathbf{B}_0



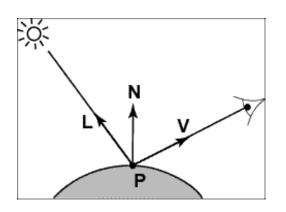
Lambert's cosine law: $\mathbf{B} = \mathbf{B}_0 \cos(\theta)$

 But appearance is the same from every angle due to larger pixel footprint at larger angles

$$\mathbf{A}_{ heta} \propto \mathbf{A}_0 \frac{1}{\cos \theta}$$

Radiance (what eye sees)
$$\propto \mathbf{B}_0 \mathbf{A}_0 \cos(\theta) \frac{1}{\cos(\theta)}$$

Final Lambertian image formation model



$$I = k_d \mathbf{N} \cdot \mathbf{L}$$

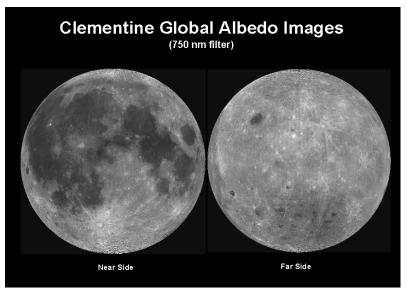


- 1. Diffuse **albedo**: what fraction of incoming light is reflected?
 - Introduce scale factor k_d
- 2. Light intensity: how much light is arriving?
 - Compensate with camera exposure (global scale factor)
- 3. Camera response function
 - Assume pixel value is linearly proportional to incoming energy (perform radiometric calibration if not)

Albedo

Sample albedos

Surface	Typical albedo
Fresh asphalt	0.04 ^[4]
Open ocean	0.06 ^[5]
Worn asphalt	0.12 ^[4]
Conifer forest (Summer)	0.08, ^[6] 0.09 to 0.15 ^[7]
Deciduous trees	0.15 to 0.18 ^[7]
Bare soil	0.17 ^[8]
Green grass	0.25 ^[8]
Desert sand	0.40 ^[9]
New concrete	0.55 ^[8]
Ocean ice	0.5–0.7 ^[8]
Fresh snow	0.80-0.90 ^[8]

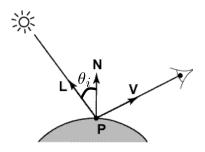


Objects can have varying albedo and albedo varies with wavelength

Source: https://en.wikipedia.org/wiki/Albedo

A Single Image: Shape from shading





Suppose (for now) $k_d=1$

$$I = k_d \mathbf{N} \cdot \mathbf{L}$$
$$= \mathbf{N} \cdot \mathbf{L}$$
$$= \cos \theta_i$$

You can directly measure angle between normal and light source

- Not quite enough information to compute surface shape
- But can be if you add some additional info, for example
 - assume a few of the normals are known (e.g., along silhouette)
 - constraints on neighboring normals—"integrability"
 - smoothness
- Hard to get it to work well in practice
 - plus, how many real objects have constant albedo?
 - But, deep learning can help

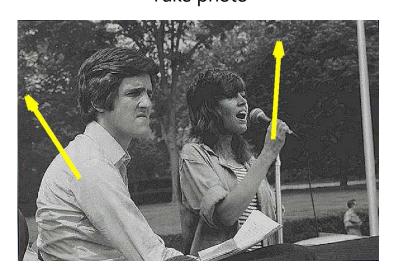




https://www.good.is/optical-illusion-plates-and-bowls-upside-down-or-not

Application: Detecting composite photos

Fake photo



Real photo



Questions?