

**CS412/CS413**  
**Introduction to Compilers**  
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**Lecture 21: Generating Pentium Code**  
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### Simple Code Generation

- Three-address code makes it easy to generate assembly
  - Complex expressions in the input program already lowered to sequences of simple IR instructions
  - Just need to translate each low IR instruction into a sequence of assembly instructions
 

e.g.  $a = p + q$   $\rightarrow$ 

```

mov 16(%ebp), %ecx
add 8(%ebp), %ecx
mov %ecx, -8(%ebp)

```
- Need to consider many language constructs:
  - Operations: arithmetic, logic, comparisons
  - Accesses to local variables, global variables
  - Array accesses, field accesses
  - Control flow: conditional and unconditional jumps
  - Method calls, dynamic dispatch
  - Dynamic allocation (new)
  - Run-time checks

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### x86 Quick Overview

- Registers:
  - General purpose 32bit: eax, ebx, ecx, edx, esi, edi
    - Also 16-bit: ax, bx, etc., and 8-bit: al, ah, bl, bh, etc.
  - Stack registers: esp, ebp
- Instructions:
  - Arithmetic: add, sub, inc, mod, idiv, imul, etc.
  - Logic: and, or, not, xor
  - Comparison: cmp, test
  - Control flow: jmp, jcc, jecz
  - Function calls: call, ret
  - Data movement: mov (many variants)
  - Stack manipulations: push, pop
  - Other: lea

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### Big Picture of Program Memory

The diagram illustrates the memory layout. On the left, a vertical stack of boxes represents the stack, containing 'Param n', 'Param 1', 'Return address', 'Previous fp', 'Local 1', and 'Local n'. To the right, 'Heap variables' are shown as a horizontal row of boxes. Below these, 'Global (static) variables' are shown as another horizontal row of boxes. Arrows indicate pointers between these memory regions.

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### Memory Layout

The diagram shows a vertical stack of memory regions. From top to bottom: 'Code', 'Static area', 'Heap', and 'Stack'. A vertical arrow on the right indicates that memory addresses decrease from 'low' at the top to 'high' at the bottom. Brackets on the left group these regions: 'Globals, Static data' (Code and Static area), 'Object fields, arrays' (Heap), and 'Locals, parameters' (Stack). Arrows on the Heap and Stack indicate their dynamic growth directions.

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### Accessing Stack Variables

- To access stack variables: use offsets from ebp
- Example:
  - $8(\%ebp)$  = parameter 1
  - $12(\%ebp)$  = parameter 2
  - $-4(\%ebp)$  = local 1

The diagram shows a stack frame with boxes for 'Param n', 'Param 1', 'Return address', 'Previous fp', 'Local 1', 'Local n', 'Param 1', and 'Param n'. Red arrows point to 'Param n' at offset 'ebp+...' and 'Param 1' at offset 'ebp+8'. Blue arrows point to 'Local 1' at offset 'ebp-4'. The 'esp' register points to the bottom of the stack.

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## Accessing Stack Variables

- Translate accesses to variables:
  - For parameters, compute offset from %ebp using:
    - Parameter number
    - Sizes of other parameters
  - For local variables, decide upon data layout and assign offsets from frame pointer to each local
  - Store offsets in the symbol table
- Example:
  - a: local, offset-4
  - p: parameter, offset+16, q: parameter, offset+8
  - Assignment  $a = p + q$  becomes equivalent to:  
 $-4(\%ebp) = 16(\%ebp) + 8(\%ebp)$
  - How to write this in assembly?

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## Arithmetic

- How to translate:  $p+q$  ?
  - Assume p and q are locals or parameters
  - Determine offsets for p and q
  - Perform the arithmetic operation
- Problem: the ADD instruction in x86 cannot take both operands from memory; notation for possible operands:
  - mem32: register or memory 32 bit (similar for r/m8, r/m16)
  - reg32: register 32 bit (similar for reg8, reg16)
  - imm32: immediate 32 bit (similar for imm8, imm16)
  - At most one operand can be mem !
- Translation requires using an extra register
  - Place p into a register (e.g. %ecx): `mov 16(%ebp), %ecx`
  - Perform addition of q and %ecx: `add 8(%ebp), %ecx`

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## Data Movement

- Translate  $a = p+q$ :
  - Load memory location (p) into register (%ecx) using a move instr.
  - Perform the addition
  - Store result from register into memory location (a):

```
mov 16(%ebp), %ecx    (load)
add 8(%ebp), %ecx    (arithmetic)
mov %ecx, -8(%ebp)   (store)
```
- Move instructions cannot take both operands from memory  
Therefore, copy instructions must be translated using an extra register:  
 $a = p \Rightarrow$  `mov 16(%ebp), %ecx`  
`mov %ecx, -8(%ebp)`
- However, loading constants doesn't require extra registers:  
 $a = 12 \Rightarrow$  `mov $12, -8(%ebp)`

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## Accessing Global Variables

- Global (static) variables are not allocated on the run-time stack
- Have fixed addresses throughout the execution of the program
  - Compile-time known addresses (relative to the base address where program is loaded)
  - Hence, can directly refer to these addresses using symbolic names in the generated assembly code
- Example: string constants

```
str: .string "Hello world!"
```

  - The string will be allocated in the static area of the program
  - Here, "str" is a label representing the address of the string
  - Can use \$str as a constant in other instructions:

```
push $str
```

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## Accessing Heap Data

- Heap data allocated with new (Java) or malloc (C/C++)
  - Such allocation routines return address of allocated data
  - References to data stored into local variables
  - Access heap data through these references
- Array accesses in Java
  - access `a[i]` requires:
    - To compute address of element:  $a + i * \text{size}$
    - And access memory at that address
  - Can use indexed memory accesses to compute addresses
  - Example: assume size of array elements is 4 bytes, and local variables a, i (offsets -4, -8)

```
a[i] = 1  ⇒  mov -4(%ebp), %ebx    (load a)
              mov -8(%ebp), %ecx    (load i)
              mov $1, (%ebx,%ecx,4) (store into the heap)
```

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## Control-Flow

- Label instructions
  - Simply translated as labels in the assembly code
  - E.g., `label2: mov $2, %ebx`
- Unconditional jumps:
  - Use jump instruction, with a label argument
  - E.g., `jmp label2`
- Conditional jumps:
  - Translate conditional jumps using `test/cmp` instructions:
    - E.g., `tjump b L` `cmp %ecx, $0`  
`jnz L`
  - where %ecx hold the value of b, and we assume booleans are represented as 0=false, 1=true

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## Run-time Checks

- Run-time checks:
  - Check if array/object references are non-null
  - Check if array index is within bounds
- Example: array bounds checks:
  - if `v` holds the address of an array, insert array bounds checking code for `v` before each load (`...=v[i]`) or store (`v[i] = ...`)
  - Assume array length is stored just before array elements:

```

cmp $0, -12(%ebp)      (compare i to 0)
jl ArrayBoundsError   (test lower bound)
mov -8(%ebp), %ecx     (load v into %ecx)
mov -4(%ecx), %ecx     (load array length into %ecx)
cmp -12(%ebp), %ecx   (compare i to array length)
jle ArrayBoundsError  (test upper bound)
...
    
```

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## X86 Assembly Syntax

- Two different notations for assembly syntax:
  - AT&T syntax and Intel syntax
  - In the examples: AT&T syntax
- Summary of differences:

Order of operands	op a, b : b is destination	op a, b : a is destination
Memory addressing	disp(base,offset,scale)	[base + offset*scale + disp]
Size of memory operands	instruction suffixes (b,w,l) (e.g., movb, movw, movl)	operand prefixes (byte ptr, word ptr, dword ptr)
Registers	%eax, %ebx, etc.	eax, ebx, etc.
Constants	\$4, \$foo, etc	4, foo, etc

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