

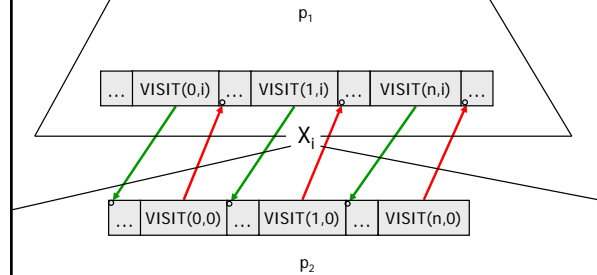
Static Attribute Evaluation

- Analyze the grammar and determine a fixed tree traversal scheme (with interleaved evaluations) such that for any possible derivation tree T , evaluations will be in topological order
- Partitioned attribute grammars are a large class that lends itself to efficient analysis and evaluation

Plans

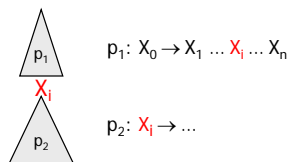
- Each production $X_0 \rightarrow X_1 \dots X_n$ will have one associated plan
- A plan is a linear sequence of instructions, where an instruction is one of
 - EVAL $X_i.a$ evaluate attribute a of symbol X_i
 - VISIT(r,i) visit neighbor i for the r -th time [child 0 = parent]
- If-then-else's in plans would permit different execution orders in different contexts, but we chose to allow only straight-line plans for simplicity and efficiency

Coroutine Relationship



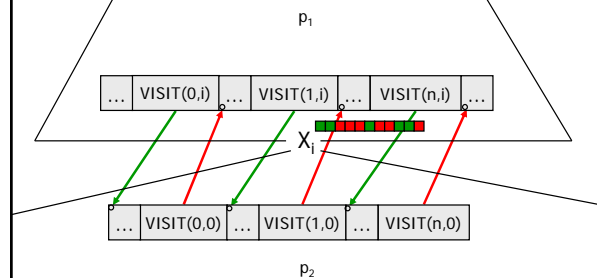
- VISIT instructions act as coroutine calls

Interface



- The attributes of X_i constitute an interface between the plans for p_1 and p_2 .
 - The plan for p_1 evaluates inherited attributes of X_i
 - The plan for p_2 evaluates synthesized attributes of X_i

Evaluation Across the Interface



- VISIT instructions act as coroutine calls

Consistency of Plans

- The plan for p_1 must be consistent with the plans for all productions

$$X_1 \rightarrow \alpha$$

- The plan for p_2 must be consistent with the plans for all productions

$$A \rightarrow \alpha X_1 \beta$$

Plans as Fragments of Topological Orders

- The plans must be constructed so that for any derivation tree T , when the plan instances are "wired up" by VISITs, the order of EVALs are a topological order for $D(T)$

AG for which no such plans exist

$$Z \rightarrow s X_1 X_2$$

$$X_1.a = X_2.d$$

$$X_1.c = 1$$

$$X_2.a = X_1.d$$

$$X_2.c = 2$$

$$Z \rightarrow t X_1 X_2$$

$$X_1.a = 3$$

$$X_1.c = X_2.b$$

$$X_2.a = 4$$

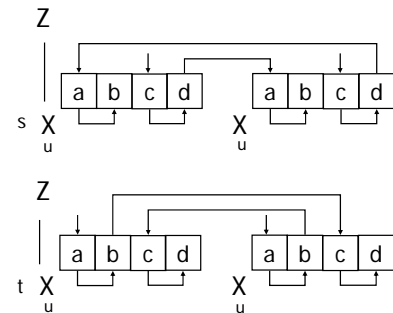
$$X_2.c = X_1.b$$

$$X \rightarrow u$$

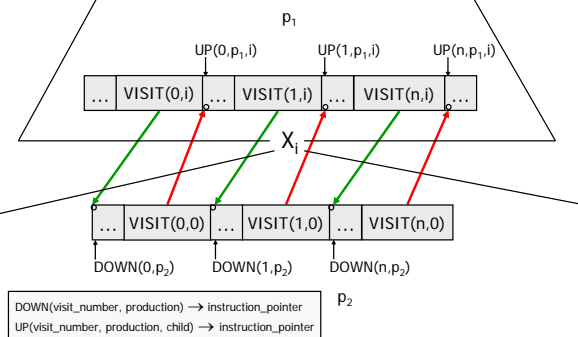
$$X.b = X.a$$

$$X.d = X.c$$

AG for which no such plans exist



UP and DOWN



Evaluator

```

node := root;
ip := DOWN(0, root.rule);
repeat
  case state of
    Xi.a: {
      evaluate Xi.a;
      increment ip;
    }
    VISIT(r,i), i>0: { /* child visit */
      ip := DOWN(r, Xi.rule);
      node := Xi;
    }
    VISIT(r,0): { /* parent visit */
      ip := UP(r, node.parent.rule, node.child_number);
      node = node.parent;
    }
  end case
until node = root and instruction at ip = VISIT(1,0);

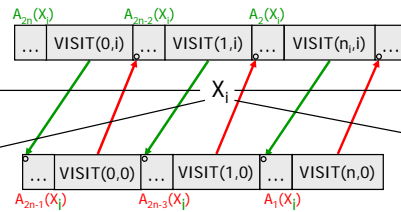
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Partitions

- If such plans are to exist, there must exist, for each nonterminal X , a partition of $A(X)$ into classes $A_{2n}(X)$, $A_{2n-1}(X)$, ..., $A_2(X)$, $A_1(X)$, where
 - even $A_i(X)$ are subsets of $IA(X)$
 - odd $A_i(X)$ are subsets of $SA(X)$

s.t., for every derivation tree T , and every nonterminal instance X in T , the attribute instances of X can be evaluated in the order $A_{2n}(X)$, $A_{2n-1}(X)$, ..., $A_2(X)$, $A_1(X)$. Within each $A_i(X)$, the order of evaluation is unconstrained and may differ from plan to plan.

Partitions in Plans



- Every plan involving X_i must respect the partitioning of $A(X)$

Partitioned Attribute Grammar

- If, in addition to the existence of the partitions, the grammar is locally acyclic, then it is called **partitioned**.

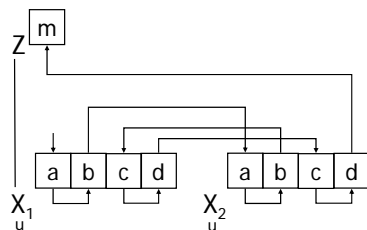
Computing Plans from Partitions

- Suppose, for each nonterminal X , we know valid partition $A_{2n}(X)$, $A_{2n-1}(X)$, ..., $A_2(X)$, $A_1(X)$
- To compute the plan for production $p: X_0 \rightarrow X_1 \dots X_n$
 - Start with D_p , the direct dependency graph of p
 - For each i in $[0..n]$, and each partition j for attributes of X_i , collapse all input attribute occurrences of the partition class $A_j(X_i)$ into one node labeled $VISIT(*,i)$ merging edges
 - Add edges between consecutive partition classes of the given X_i
 - Topological sort the resulting graph and fill in visit numbers in place of $*$'s

Example

$Z \rightarrow X_1 X_2$
 $X_1.a = 1$
 $X_2.a = X_1.b$
 $X_1.c = X_2.b$
 $X_2.c = X_1.d$
 $S.m = X_2.d$

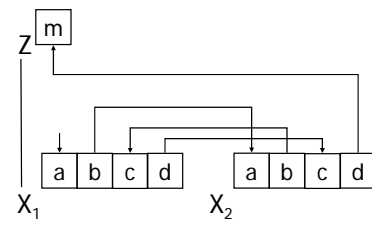
$X \rightarrow u$
 $X.b = X.a$
 $X.d = X.c$



Partitioning of $A(X) = \{\{a\}\{b\}\{c\}\{d\}\}$

Example

$Z \rightarrow X_1 X_2$



Partitioning of $A(X) = \{\{a\}\{b\}\{c\}\{d\}\}$

Example

$Z \rightarrow X_1 X_2$

Partitioning of $A(X) = \{\{a\}\{b\}\{c\}\{d\}\}$

Plan: $\text{Eval}(X_1.a); \text{Visit}(0,1); \text{Eval}(X_2.a); \text{Visit}(0,2);$
 $\text{Eval}(X_1.c); \text{Visit}(1,1); \text{Eval}(X_2.c); \text{Eval}(Z.m); \text{Visit}(0,0)$

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Ordered Attribute Grammars

- For each nonterminal X
 - Construct graph $DS(X) = \langle A(X), E \rangle$ that over-approximates the transitive dependencies that may arise among the attributes of X in some derivation tree
 - Defer how.
 - If $DS(X)$ is cyclic for any X give up.

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OAG: step 1

- For each nonterminal X
 - Construct a graph $DS(X) = \langle A(X), E \rangle$ that over-approximates the transitive dependencies that may arise among the attributes of X in some derivation tree
 - Defer how.
 - If $DS(X)$ is cyclic for any X give up.

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OAG: step 2

- Attempt to compute a partition from $DS(X)$ without reference to the productions in which X occurs, as follows:
 - Topological sort $DS(X)$ minimizing alternations between $IA(X)$ and $SA(X)$.
 - Each switch from inherited to synthesized (or vice versa) is a boundary between classes of the partition.

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OAG: step 3

- Use the given method for finding a plan from the partitions. If this fails (because topological sort discovers a cycle), then fail.

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OAG: step 1, cont.

- To compute $DS(X)$ for all X
 - Simultaneously take transitive closures of the direct dependence graphs D_p for all p , and whenever an edge between two attributes of the same nonterminal occurrence is created, add it to **every** occurrence of X .
 - When finished, choose the attributes and edges of an arbitrary occurrence of each nonterminal X as $DS(X)$

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