

# CS 409: Data Structures and Algorithms

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There's a handout that tells you everything you need to know for now about the course structure:

- TAs and consultants
- Office hours
- Grading
- Text
- How to find out more
  - Check the course web site and newsgroup!

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## Required Background

I will assume you know basic properties of:

- Basic functions ( $\lfloor x \rfloor$ ,  $\lg n$ ,  $2^n$ ,  $n!$ ) (Ch. 2.2)
- Summations (Ch. 3)
  - Summation notation:  $\sum_{k=1}^n k$
  - Technique for bounding sums:  $\sum_{k=1}^n k < n^2$ .
    - \* including approximation by integrals
- Sets, relations, functions, graphs, trees (Ch. 5)
  - manipulating intersection, union, complement
  - reflexive, symmetric, transitive relations
  - injection, bijection, one-to-one correspondence
  - degree, connected component, (un)directed graph
  - binary trees
- Counting and Probability (Chapter 6.1-6.4)
  - choosing  $k$  out of  $n$
  - axioms of probability
  - conditional probability and independence
  - expected value
  - binomial distribution

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## What's It All About?

In a nutshell:

- designing and analyzing algorithms for solving computational problems.

Such algorithms deal with *data*.

- That means we need good *data structures*
  - ways of storing and accessing the data to make the algorithm efficient

We consider some key data structures and efficient ways of implementing them:

- stacks, queues, linked lists, hash tables, binary search trees, binomial heaps, . . .

Data structures are the building blocks for many algorithms, so it's worth optimizing them.

We apply data structures to important problems (graph algorithms, sorting, prioritizing, string matching, . . .)

Programming is an important component of this course!

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A word to the wise:

- Review this material NOW!
- Make sure you can do all the review problems
- See me or someone else on staff if you can't

CS211 is a prerequisite for the course.

- There is some overlap in topics covered
  - I will cover some topics in greater depth (e.g., hashing), and briefly review others (e.g., breadth-first and depth-first search)

CS280 is also a prerequisite:

- You need to know how to do induction
- We will cover Minimum Spanning Trees and Dijkstra's algorithm (sometimes done in CS280)

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## An Example: Sorting

**Given:** A sequence of  $n$  numbers  $\langle a_1, \dots, a_n \rangle$

**Output:** A permutation (reordering)  $\langle a'_1, \dots, a'_n \rangle$  such that  $a'_1 \leq \dots \leq a'_n$ .

A naive (but common) approach: Insertion Sort.

- Assume we've sorted the first  $k$  elements; put the  $(k+1)$ st element into the right place by comparing it until we find the right place for it.

Suppose  $A = \langle a_1, \dots, a_n \rangle$  is an array to be sorted.

- $A[i] = a_i$

INSERTION-SORT( $A$ )

```

1 for  $j \leftarrow 2$  to  $\text{length}[A]$ 
2   do  $\text{key} \leftarrow A[j]$ 
3     ▷ Insert  $A[j]$  into sorted sequence  $A[1..j-1]$ .
4      $i \leftarrow j-1$ 
5     while  $i > 0$  and  $A[i] > \text{key}$ 
6       do  $A[i+1] \leftarrow A[i]$ 
7          $i \leftarrow i-1$ 
8      $A[i+1] \leftarrow \text{key}$ 

```

Suppose  $A = \langle 5, 2, 4, 6, 1 \rangle$ .

5 2 4 6 1      $j = 2; \text{key} = 2$

2 5 4 6 1      $j = 3; \text{key} = 4$

2 4 5 6 1      $j = 4; \text{key} = 6$

2 4 5 6 1      $j = 5; \text{key} = 1$

1 2 4 5 6

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## Running Time of Insertion Sort

Assume step  $i$  in the algorithm “costs”  $c_i$

Let  $t_j$  be number of times  $j$ th inner loop is executed

- $t_j$  depends on the input  $A$
- best case:  $t_j = 1$
- worst case:  $t_j = j$

|   |   |       |                          |
|---|---|-------|--------------------------|
| 1 | for $j \leftarrow 2$ to $\text{length}[A]$            | $c_1$ | $n$                      |
| 2 | do $\text{key} \leftarrow A[j]$                       | $c_2$ | $n-1$                    |
| 3 | ▷ Insert $A[j]$ into sorted<br>sequence $A[1..j-1]$ . | 0     | $n-1$                    |
| 4 | $i \leftarrow j-1$                                    | $c_4$ | $n-1$                    |
| 5 | while $i > 0$ and $A[i] > \text{key}$                 | $c_5$ | $\sum_{j=2}^n t_j$       |
| 6 | do $A[i+1] \leftarrow A[i]$                           | $c_6$ | $\sum_{j=2}^n (t_j - 1)$ |
| 7 | $i \leftarrow i-1$                                    | $c_7$ | $\sum_{j=2}^n (t_j - 1)$ |
| 8 | $A[i+1] \leftarrow \text{key}$                        | $c_8$ | $n-1$                    |

Let  $T(A)$  be the running time on input  $A$ :

$$T(A) = c_1 n + (c_2 + c_4 + c_8 - c_6 - c_7)(n-1) + (c_5 + c_6 + c_7) \sum_{j=1}^{n-1} t_j$$

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$$T(A) = c_1 n + (c_2 + c_4 + c_8 - c_6 - c_7)(n-1) + (c_5 + c_6 + c_7) \sum_{j=1}^{n-1} t_j$$

Best case:  $t_j = 1$

$$T(A) = c_1 n + (c_2 + c_4 + c_5 + c_8)(n-1) = (c_1 + c_2 + c_4 + c_5 + c_8)n - (c_2 + c_4 + c_5 + c_8)$$

Worst case:  $t_j = j$

$$T(A) = (c_5 + c_6 + c_7) \sum_{j=2}^{n-1} j + \dots = (c_5 + c_6 + c_7) \left( \frac{n(n+1)}{2} - 1 \right) + \dots$$

- Quadratic is OK if  $n$  is 5, 10, 100.
- But what if  $n = 1,000,000$ ?

Average case:

- When we insert  $A[j]$ , roughly half the elements in  $A[1..j-1]$  will be greater than  $A[j]$ , and half will be less.

$$\circ t_j \sim j/2$$

- Average case is still quadratic

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## Designing Algorithms

Insertion sort uses an *incremental* approach:

- We insert a single element into  $A[1..j]$ .

We can do better using “divide-and-conquer”

- *Divide* each problem into smaller subproblems (typically about half the size of the original)
- *Conquer* each subproblem
- *Combine* the solutions

## Merge Sort

*Merge sort* is a sorting algorithm that uses divide and conquer.

- *Divide* the sequence to be sorted into two subsequences of size  $n/2$
- *Conquer*: sort the two subsequence (recursively)
- *Combine*: merge the resulting sequences

Suppose  $A$  is an array of length  $n$ ,  $1 \leq p \leq r \leq n$ :

MERGE-SORT( $A, p, r$ )

```
1 if  $p < r$ 
2   then  $q \leftarrow \lfloor (p+r)/2 \rfloor$ 
3     MERGE-SORT( $A, p, q$ )
4     MERGE-SORT( $A, q+1, r$ )
5     MERGE( $A, p, q, r$ )
```

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## Analysis of Merge-Sort

MERGE-SORT( $A, p, r$ )

```
1 if  $p < r$ 
2   then  $q \leftarrow \lfloor (p+r)/2 \rfloor$ 
3     MERGE-SORT( $A, p, q$ )
4     MERGE-SORT( $A, q+1, r$ )
5     MERGE( $A, p, q, r$ )
```

If  $m = r - p + 1$ , define

- $T(m)$  = the worst-case time for MERGE-SORT( $A, p, r$ )
- $U(m)$  = be the worst-case time for MERGE( $A, p, q, r$ )

$$T(m) = \begin{cases} c_1 & \text{if } m = 1 \\ 2T(\lceil m/2 \rceil) + U(m) & \text{if } m > 1 \end{cases}$$

Not hard to show that  $U(m) = \Theta(m)$

It follows that  $T(n) = \Theta(n \lg n)$  ( $\lg = \log_2$ )

- This is much better than  $\Theta(n^2)$  for large  $n$ !

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## What We'll Cover

- Data structures (Chapters 7, 11–14, 22)
  - Stacks, queues, linked lists
  - Hashing
  - Binary search trees, red-black trees (maybe)
  - Heaps
- Algorithm design techniques (Chapters 16–18)
  - dynamic programming
  - greedy algorithms
  - amortized analysis
- Graph algorithms (Chapters 23–25, 27)
  - Strongly connected components
  - Minimum spanning tree
  - Shortest paths (Dijkstra's algorithm)
  - Maximum flow

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- NP-completeness (Chapter 36)
- If there's time:
  - String Matching (Chapter 34)
  - The RSA cryptosystem (Chapter 33.7)

This week:

- Technical background
  - Asymptotic growth (big  $O, \Theta, \Omega$ ) (Chapter 2.1)
  - Recurrences (Chapter 4.1, 4.3)
  - A little probability

## Asymptotic Notation

We measure the efficiency of an algorithm as a function of the input size.

- Want to describe the efficiency succinctly

Some useful notation:

- $T(n) = O(g(n)) / \Omega(g(n)) / \Theta(g(n))$  if there is a constant  $c$  such that  $cg(n)$  is asymptotically an upper/lower/tight bound for  $T(n)$ 
  - $T(n) = \Theta(g(n))$  iff  $T(n) = O(g(n))$  and  $T(n) = \Omega(g(n))$ .

We won't cover  $o(g(n)), \omega(g(n))$ .

Formally,  $\Theta(g(n)), O(g(n))$ , and  $\Omega(g(n))$  are sets of functions:

- $\Theta(g(n)) = \{f(n) : \exists c_1, c_2 > 0, n_0 (c_1g(n) \leq f(n) \leq c_2g(n) \text{ for } n \geq n_0)\}$
- $O(g(n)) = \{f(n) : \exists c_2 > 0, n_0 (f(n) \leq c_2g(n) \text{ for } n \geq n_0)\}$
- $\Omega(g(n)) = \{f(n) : \exists c_1 > 0, n_0 (c_1g(n) \leq f(n) \text{ for } n \geq n_0)\}$

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**Example:**  $2n^2 + 3n + 1 = \Theta(n^2) = 2n^2 + \Theta(n)$ .

- Clearly  $2n^2 \leq 2n^2 + 3n + 1 \leq 3n^2$  for  $n \geq 4$ 
  - Since  $n^2 \geq 3n + 1$  if  $n \geq 4$
- Also  $2n^2 + 3n \leq 2n^2 + 3n + 1 \leq 2n^2 + 4n$

More generally, if  $a > 0$ ,

$$an^2 + bn + c = \Theta(n^2) = an^2 + \Theta(n)$$

**Example:**  $6n^3 \neq \Theta(n^2)$ ;  $6n^3 = \Omega(n^2)$ .

- Really should say  $6n^3 \notin \Theta(n^2)$ ;  $6n^3 \in \Omega(n^2)$ .

The  $O, \Theta, \Omega$  notation ignores constants.

- The constants depend on the machine, details of implementation
- Improving the constants is good but ...
- Improving  $\Theta(\dots)$  is better
  - It gives us a better indication of how the problem scales
  - $\Theta(\lg n) < \Theta(\lg^2 n) < \Theta(n) < \Theta(n \lg n) < \Theta(n^2) < \Theta(2^n)$

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## Recurrences

A *recurrence* is a relation that describes a function in terms of its value on smaller inputs.

$$T(m) = \begin{cases} c_1 & \text{if } m = 1 \\ 2T(\lceil m/2 \rceil) + c_2m & \text{if } m > 1 \end{cases}$$

Recurrences arise frequently when computing the running time of a recursive algorithm.

- Often stated without  $\lceil \cdot \rceil$ ,  $\lfloor \cdot \rfloor$

How do we solve them?

- Guess and verify by induction (substitution method)
- Apply master theorem

We won't cover iteration method.

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## The Master Method

**Theorem:** Let  $a, b \geq 1$  and suppose

$$T(n) = aT(n/b) + f(n).$$

- Can replace  $n/b$  by  $\lceil n/b \rceil$  or  $\lfloor n/b \rfloor$ .
1. If  $f(n) = O(n^{\log_b(a)-\epsilon})$  for some  $\epsilon > 0$  then  $T(n) = \Theta(n^{\log_b(a)})$ .
  2. If  $f(n) = \Theta(n^{\log_b(a)})$  then  $T(n) = \Theta(n^{\log_b(a)} \lg n)$ .
  3. If  $f(n) = \Omega(n^{\log_b(a)+\epsilon})$  for some  $\epsilon > 0$  and  $af(n/b) \leq cf(n)$  for some  $c > 1$  then  $T(n) = \Theta(f(n))$ .

In all three cases we compare  $f(n)$  with  $n^{\log_b(a)}$ .

- The larger function dominates

Roughly:

- if  $f(n) \ll n^{\log_b(a)}$ , then  $T(n) = \Theta(n^{\log_b(a)})$
- if  $f(n) \sim n^{\log_b(a)}$ , then  $T(n) = \Theta(n^{\log_b(a)} \lg n)$
- if  $f(n) \gg n^{\log_b(a)}$ , then  $T(n) = \Theta(f(n))$

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## The Substitution Method

$$T(n) = \begin{cases} c_1 & \text{if } m = 1 \\ 2T(n/2) + n & \text{if } m > 1 \end{cases}$$

Guess  $T(n) \leq cn \lg(n)$  (for some  $c$ ):

Verify:

$$\begin{aligned} T(n) &= 2T(n/2) + n \\ &\leq 2c(n/2 \lg n/2) + n \\ &= cn \lg(n/2) + n \\ &= cn \lg n + n - cn \lg 2 \\ &= cn \lg n + (1 - c)n \\ &\leq cn \lg n \quad (\text{if } c \geq 1) \end{aligned}$$

What about  $T(1)$ ?

- $c \lg 1 = 0$

All we need is  $T(n) \leq cn \lg n$  for  $n$  sufficiently large.

- E.g.  $T(2) = 2c_1 + 2$ . Choose  $c = c_1 + 1$ .

$$\circ \text{ Then } T(2) \leq 2c \lg 2 = 2c_1 + 2$$

A formal proof that  $T(n) \leq cn \lg n$  for  $n \geq 2$  proceeds by induction.

- YOU ALL SHOULD KNOW HOW TO DO INDUCTION PROOFS!

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$$T(n) = aT(n/b) + f(n):$$

1. If  $f(n) = O(n^{\log_b(a)-\epsilon})$  for some  $\epsilon > 0$  then  $T(n) = \Theta(n^{\log_b(a)})$ .
2. If  $f(n) = \Theta(n^{\log_b(a)})$  then  $T(n) = \Theta(n^{\log_b(a)} \lg n)$ .
3. If  $f(n) = \Omega(n^{\log_b(a)+\epsilon})$  for some  $\epsilon > 0$  and  $af(n/b) \leq cf(n)$  for some  $c > 1$  then  $T(n) = \Theta(f(n))$ .

Comments:

- $f(n) \ll n^{\log_b(a)}$  means there is some polynomial  $n^\epsilon$  such that  $f(n) \leq cn^{\log_b(a)}/n^\epsilon$
- Third case has a regularity condition:  $af(n/b) \leq cf(n)$
- Not all cases covered by theorem—but it's still very useful

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$$T(n) = aT(n/b) + f(n):$$

1. If  $f(n) = O(n^{\log_b(a)-\epsilon})$  for some  $\epsilon > 0$   
then  $T(n) = \Theta(n^{\log_b(a)})$ .
2. If  $f(n) = \Theta(n^{\log_b(a)})$  then  $T(n) = \Theta(n^{\log_b(a)} \lg n)$ .
3. If  $f(n) = \Omega(n^{\log_b(a)+\epsilon})$  for some  $\epsilon > 0$  and  
 $af(n/b) \leq cf(n)$  for some  $c > 1$   
then  $T(n) = \Theta(f(n))$ .

**Examples:**

- $T(n) = 9T(n/3) + n$ 
  - $a = 9, b = 3, f(n) = n$
  - $n^{\log_3(9)} = n^2$ , so  $f(n) = O(n^{\log_3(9)-\epsilon})$
  - $T(n) = \Theta(n^2)$
- $T(n) = T(2n/3) + 1$ 
  - $a = 1, b = 3/2, f(n) = 1 = n^{\log_{3/2}(1)}$
  - $T(n) = \Theta(\lg n)$
- $T(n) = 3T(n/4) + n \lg n$ 
  - $a = 3, b = 4, f(n) = n \lg n$
  - $n^{\log_4 3} \sim n^{0.793}$ ;  $f(n) = \Omega(n^{0.793+\epsilon})$
  - $af(n/b) = 3(n/4) \lg(n/4) \leq (3/4)n \lg n = 3/4 f(n)$
  - $T(n) = \Theta(n \lg n)$

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$$T(n) = aT(n/b) + f(n):$$

1. If  $f(n) = O(n^{\log_b(a)-\epsilon})$  for some  $\epsilon > 0$   
then  $T(n) = \Theta(n^{\log_b(a)})$ .
2. If  $f(n) = \Theta(n^{\log_b(a)})$  then  $T(n) = \Theta(n^{\log_b(a)} \lg n)$ .
3. If  $f(n) = \Omega(n^{\log_b(a)+\epsilon})$  for some  $\epsilon > 0$  and  
 $af(n/b) \leq cf(n)$  for some  $c > 1$   
then  $T(n) = \Theta(f(n))$ .

- $T(n) = 2T(n/2) + n \lg n$ 
  - $a = b = 2, f(n) = n \lg n$
  - $n^{\log_2(2)} = n^1$ ;
  - \*  $n \lg n \neq O(n^{1-\epsilon})$
  - \*  $n \lg n \neq \Theta(n)$
  - \*  $n \lg n \neq \Omega(n^{1+\epsilon})$
- Theorem does not apply!

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## Random Variables and Expectation: A Review

Suppose  $S$  is a sample space with a probability  $\Pr$

Remember: a *random variable*  $X$  on  $S$  is a function from  $S$  to the real numbers.

- $\Pr(X = x) = \Pr(\{s \in S : X(s) = x\})$
- Example: toss a pair of fair dice.
  - Let  $S$  be the set of 36 outcomes:  $(1, 1), (1, 2), \dots$
  - Let  $X(a, b) = a + b$
  - $\Pr(X = 4) = \Pr(\{(1, 3), (2, 2), (3, 1)\}) = 1/12$

The expected value of  $X$  is

$$E(X) = \sum_x x \Pr(X = x).$$

- For  $X(a, b) = a + b$ 

$$E(X) = 2(1/36) + 3(2/36) + 3(3/36) + \dots$$

$$+ 7(6/36) + \dots + 12(1/36)$$

When we talk about the average-case running time of an algorithm, we mean the expectation.

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## Dynamic Sets

- A *dynamic set* is one whose membership changes over time.
- Sometimes the elements of a dynamic set have an associated *key*
  - In that case, we write  $key[x] = k$
- Sometimes keys come from a totally ordered set
  - this means  $key[x] > key[x']$ ,  $key[x] < key[x']$  or  $key[x] = key[x']$

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## Dynamic Set Operations

We want to be able to manipulate dynamic sets.

Typical operations:

- $\text{SEARCH}(S, k)$ : returns  $x \in S$  such that  $\text{key}[x] = k$  if there is one;  $\text{NIL}$  otherwise
  - typically  $x$  is a pointer to an element in  $S$ , not the element itself
- $\text{INSERT}(S, x)$
- $\text{DELETE}(S, x)$
- $\text{MINIMUM}(S)$ : returns element with smallest key
- $\text{MAXIMUM}(S)$ : returns element with largest key
- $\text{SUCCESSOR}(S, x)$
- $\text{PREDECESSOR}(S, x)$ 
  - $\text{MINIMUM}$ ,  $\text{MAXIMUM}$ ,  $\text{PREDECESSOR}$ , and  $\text{SUCCESSOR}$  make sense only if the keys are totally ordered

We do not necessarily want or need to implement all these operations.

- Different data types implement different subsets
- A *dictionary* allows insert, delete, and search
- A priority queue allows insert, delete, maximum
- There are typically tradeoffs between implementations