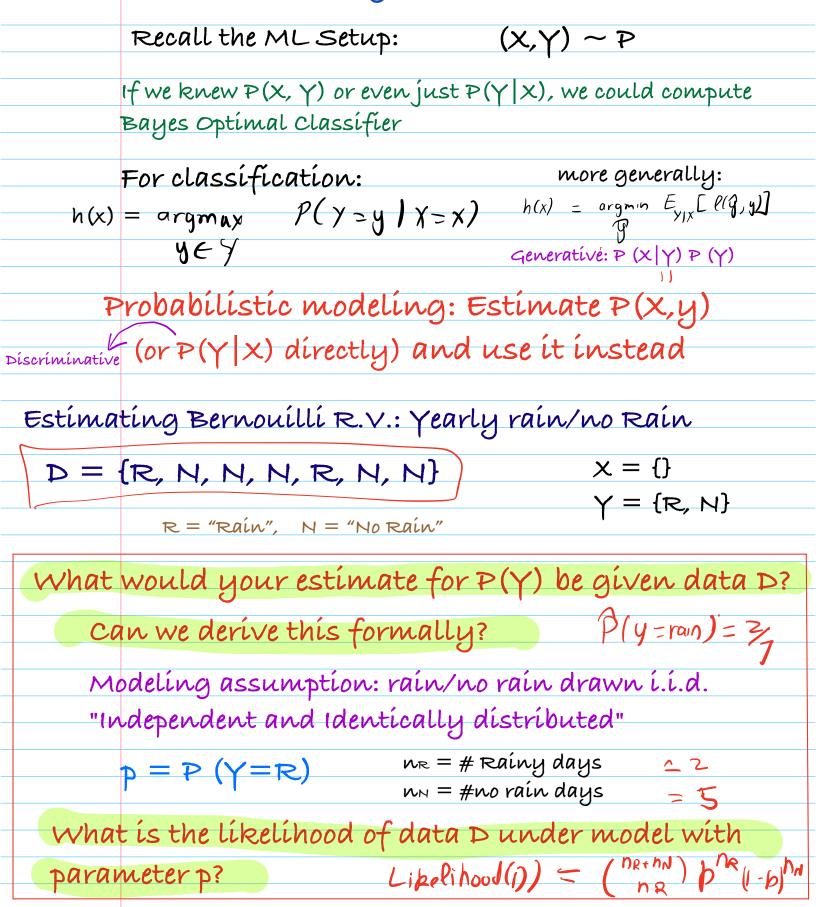
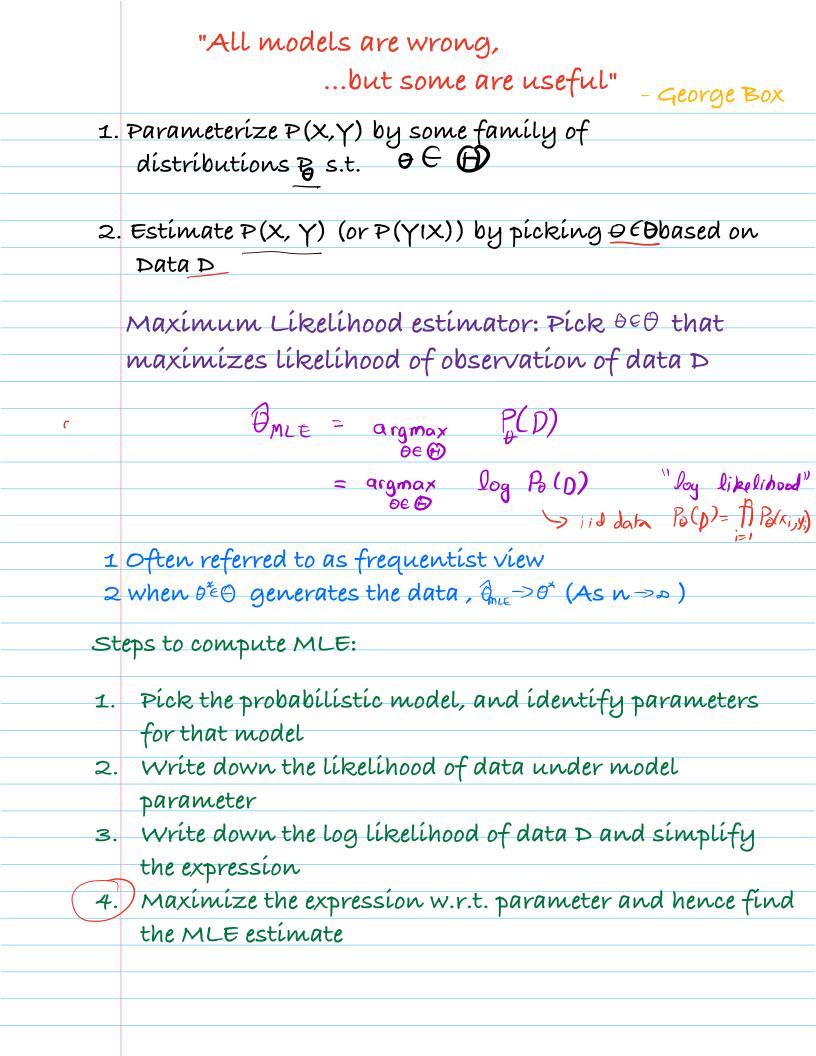
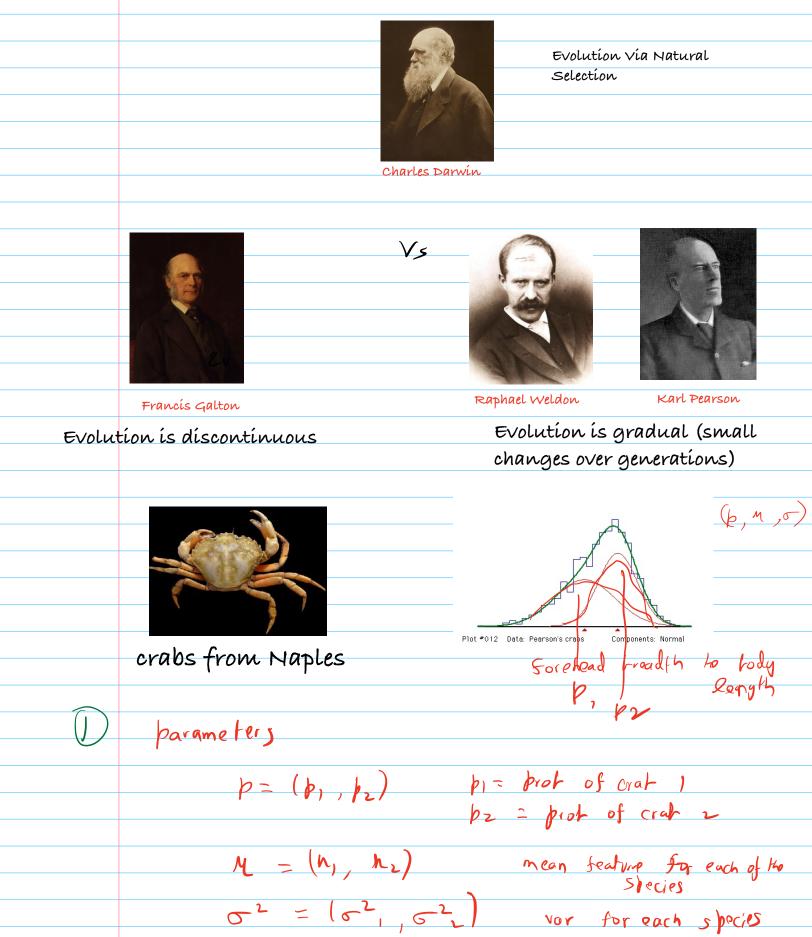
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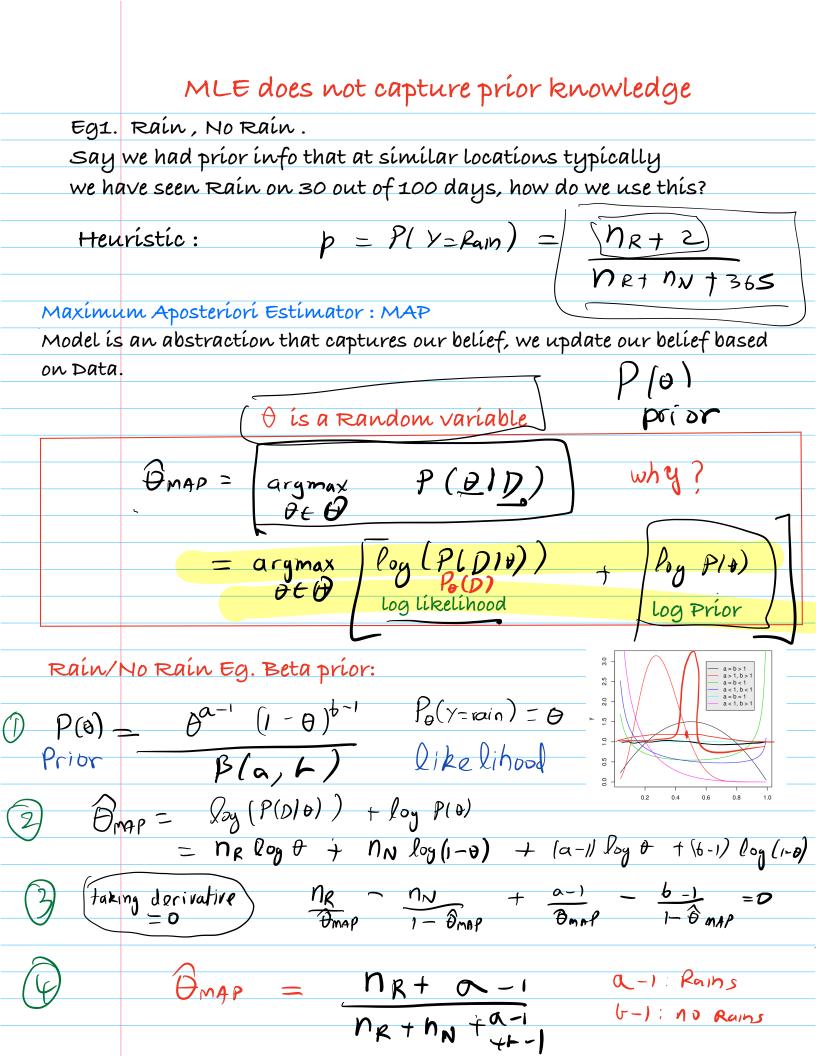
Probabilistic modeling, MLE and MAP Estimates





Gaussian Mixture Model :





Often MAP is referred to as Bayesian view There is Bayesian and there is BAYESIAN True Bayesían: "There ís no model, all you are estimating is y". $P(Y|X, p) = \int_{\Theta} P(Y, \Theta|X, p) d\theta$ = $\int_{\Theta} P(Y|\theta, X, p) P(\theta|p) d\theta$ $p_{nk} = argmnx Og \left(\begin{pmatrix} n_{k} n_{k} \end{pmatrix} p^{n_{k}} \left(1 - p \right)^{n_{k}} \right)$ = argmax la (nR+MA) + n, log (p) + n, lo(1-p) $\frac{d(n_R \log p + n_N \log(1-p))}{2} = 0$ To oftimise db

- n_N ヨロ P = NR 1 NR + hN h(x) = argmax $y \in Y$ Y=y1 K) Pen LE P P(O)D arymax loy argmax P(2) = argmax log/P plo > CD - argmax log Plying De log likeling t ley

log argmax M, 52 ſ Nσ M,o Ъ =0 Ŵ d -0 7 70 Э X A . κ*΄* g б

 $\theta = \frac{1}{2}$ - 1 + $\left[\chi_{j} \right]$ 6 r $= P(p) \theta$ P(+, $= \arg \max_{\Theta} \frac{P(\Psi)}{P(\Theta)} \frac{P(\Psi)}{P(\Theta)}$ argmax P(+

= argmax log P(DID) P(D) = argmax log P(D)D) flg Ploj