1/0

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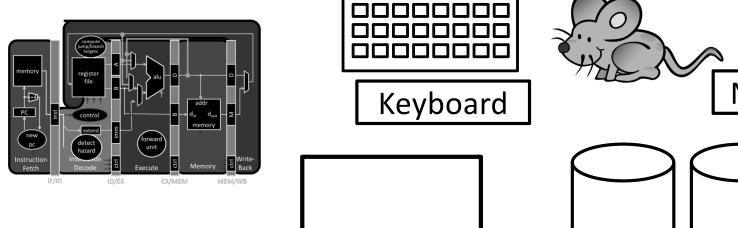
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Big Picture: Input/Output (I/O)

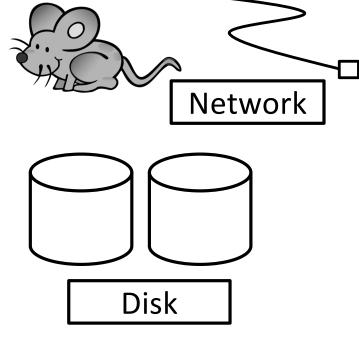
How does a processor interact with its environment?

Computer System =

Memory + Datapath + Control + Input + Output



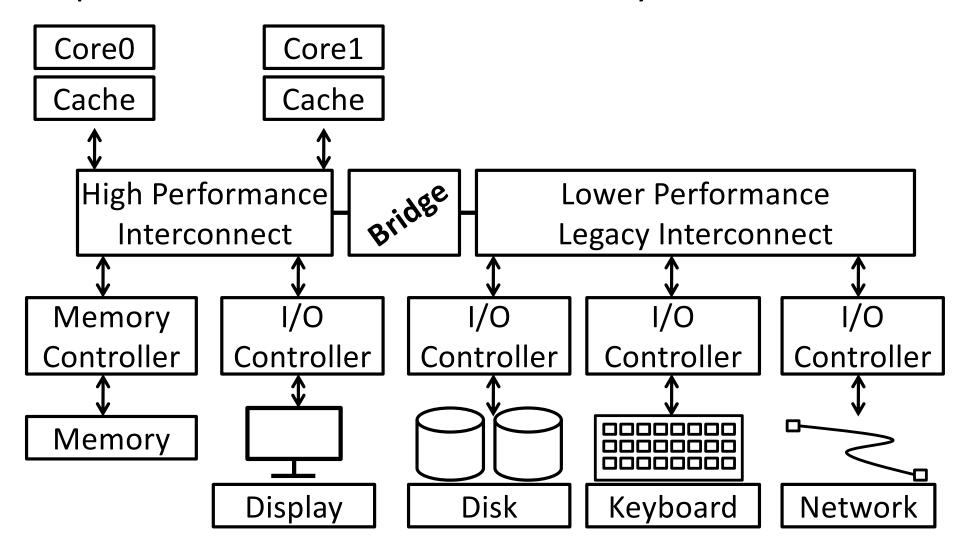
Display



Putting it all together

I/O connected with I/O Controllers

high-performance interconnect: processor, memory, display lower-performance interconnect: disk, keyboard, network



Bus Types

Processor – Memory ("Front Side Bus")

- Short, fast, & wide
- Mostly fixed topology, designed as a "chipset"
 - CPU + Caches + Interconnect + Memory Controller

I/O and Peripheral busses (PCI, SCSI, ...)

- Longer, slower, & narrower
- Flexible topology, multiple/varied connections
- Interoperability standards for devices
- Connect to processor-memory bus through a bridge

I/O Device API

Typical I/O Device API

a set of read-only or read/write registers

Command registers

writing causes device to do something

Status registers

• reading indicates what device is doing, error codes, ...

Data registers

- Write: transfer data to a device
- Read: transfer data from a device

Every device uses this API

How to talk to a device?

1. Programmed I/O:

special instructions talk over special busses Specify: device, data, direction

• inb \$a, 0x64 (keyboard status register)

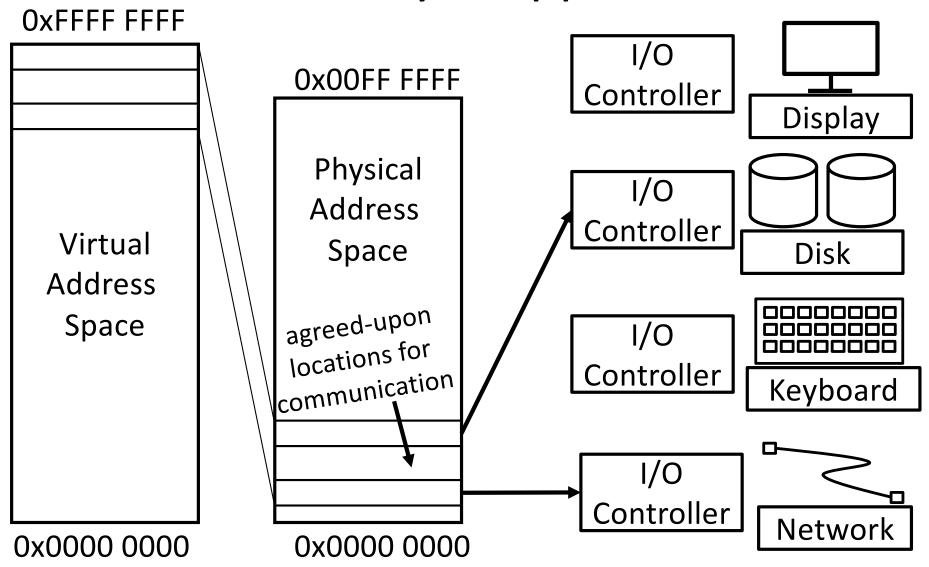
- outb \$a, 0x60 (keyboard data register)
- Protection: only allowed in kernel mode (expensive)

2. Memory-Mapped I/O:

map registers into virtual address space

- Accesses to certain addresses redirected to I/O devices
- Data goes over the memory bus (faster!)
- Protection: via bits in pagetable entries
- OS+MMU+devices configure mappings

Memory-Mapped I/O



vs. less-favored alternative = Programmed I/O:

- Syscall instructions that communicate with I/O
- Communicate via special device registers

Device Drivers

```
Memory Mapped I/O
Programmed I/O
                              struct kbd {
char read_kbd()
                                char status, pad[3];
                                char data, pad[3];
do {
                              };
    sleep();
                              kbd *k = mmap(...); 
    status = jhb(0x64);
                                                    syscall
  } while(!/status & 1));
                              char read kbd()
  returninb(0x60);
                                do {
} syscalls
                                  sleep();
Clicker Question: Which is better?
                                  status = k->status;
                                } while(!(status & 1));
 (A) Programmed I/O
 (B) Memory Mapped I/O
                                return k->data;
 (C) Both have syscalls, both are bald
```

I/O Data Transfer

How to talk to device?

Programmed I/O or Memory-Mapped I/O

How to get events?

Polling or Interrupts

How to transfer lots of data?

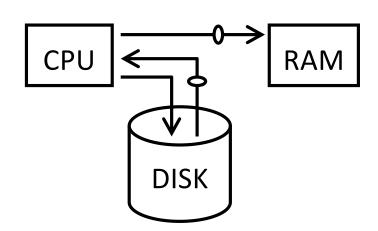
```
disk->cmd = READ_4K_SECTOR;
disk->data = 12;
while (!(disk->status & 1) { }
for (i = 0..4k)
buf[i] = disk->data;
```

Data Transfer

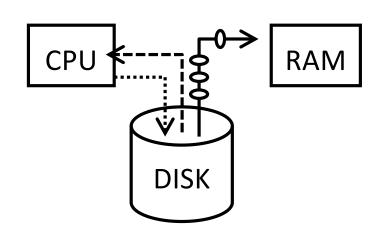
1. Programmed: Device $\leftarrow \rightarrow$ CPU $\leftarrow \rightarrow$ RAM Transfer

for
$$(i = 1 ... n)$$

- CPU issues read request
- Device puts data on bus
 & CPU reads into registers
- CPU writes data to memory



- 2. Direct Memory Access (DMA): Device $\leftarrow \rightarrow$ RAM
 - CPU sets up DMA request
 - for (i = 1 ... n)
 Device puts data on bus
 & RAM accepts it
 - Device interrupts CPU after done



Programmed I/O vs Memory Mapped I/O

Programmed I/O

- Requires special instructions
- Can require dedicated hardware interface to devices
- Protection enforced via kernel mode access to instructions
- Virtualization can be difficult

Memory-Mapped I/O

- Re-uses standard load/store instructions
- Re-uses standard memory hardware interface
- Protection enforced with normal memory protection scheme
- Virtualization enabled with normal memory virtualization scheme

Polling vs. Interrupts

How does program learn device is ready/done?

- 1. Polling: Periodically check I/O status register
 - Common in small, cheap, or real-time embedded systems
 - + Predictable timing, inexpensive
 - Wastes CPU cycles
- 2. Interrupts: Device sends interrupt to CPU
 - Cause register identifies the interrupting device
 - Interrupt handler examines device, decides what to do
 - + Only interrupt when device ready/done
 - Forced to save CPU context (PC, SP, registers, etc.)
 - Unpredictable, event arrival depends on other devices' activity

Clicker Question: Which is better?

(A) Polling (B) Interrupts (C) Both equally good/bad