2. The main message of this lecture:

A syntactic correctness of a program is easy to verify (compilers do it). A semantic correctness stating that the program will be producing the right output is impossible to verify automatically. Semantic correctness usually consists of two parts: a partial correctness stating that the correct answer is obtained if the program terminates, and a proof that the program always terminates.

Proving semantical correctness automatically is impossible.

**Theorem 16.1.** There is no algorithm to decide, given any program P and input x, whether P will eventually halt.

**Proof.** Imagine an operating system  $\Phi$  capable of compiling and executing any program P on any input y. Since every input is a string of characters in a special input alphabet, we may regards  $\Phi$  as a function of two string arguments x = the code of a program P, and y = an input of P such that for any given  $x \Phi(x, y) \cong P(y)$ . Here  $\cong$  means that both parts are simultaneously defined or not defined, and if they are defined their values coincide. Suppose the halting problem is decidable, then there is a computable function f(x) from strings to  $\{0, 1\}$ :

$$f(x) = \begin{cases} 0, & \text{if } \Phi(x, x) \text{ halts} \\ 1, & \text{if } \Phi(x, x) \text{ does not halt} \end{cases}$$

Consider another function g(x) such that

$$g(x) = \begin{cases} 0, & \text{if } f(x) = 1, \\ loops \text{ forever}, & \text{if } f(x) = 0 \end{cases}$$

Here is a description of a program that computes g: "Given  $x \operatorname{run} f(x)$ . If f(x) = 1, print 0 and halt. Otherwise, loop forever." Let i be a program code for g. Then

$$\Phi(i,i) \ \text{halts} \ \Leftrightarrow \ g(i) = 0 \ \ \Leftrightarrow \ f(i) = 1 \ \Leftrightarrow \ \Phi(i,i) \ \text{does not halt},$$

which contradicts the assumption that the halting problem is decidable.

**Definition 16.2.** A program segment S is said to be **partially correct** with respect to the **initial assertion** p and the **final assertion** q if whenever p holds for the initial values of S and S terminates, then q holds for the output values of S. Notation:  $p\{S\}q$  is also known as the **Hoare implication**<sup>1</sup>

**Example 16.3.** Show that the program segment S y := 2the initial assertion x = 3 and the final assertion z = 5. Termination is obvious since there are not loops there and the execution stops after performing

Termination is obvious since there are not loops there and the execution stops after performing the assignments. The partial correctness means that the Hoare implication  $p\{S\}q$  holds in this

<sup>&</sup>lt;sup>1</sup>Tony Hoare, an Oxford professor, was recently knighted by the British Queen.

case. Note, that S in fact depends on x, therefore S = S(x), and a more proper notation for the Hoare implication would be  $p\{S(p)\}q$ . A simple analysis of the assignments made by S immediately convinces us that if p (i.e. x = 3) holds before S has been executed, then q (i.e. z = 5) holds afterwards. Therefore,  $p\{S\}q$  is true.

A general strategy of proving correctness of a program P is **decomposing** P into smaller manageable segments  $S_1, S_2, S_3...$  corresponding to elementary programmistic steps: assignments, loops, conditional branching, etc. and then proving every segment  $S_i$  correct for corresponding matching initial and final assertions. Each elementary segment is treated by its own **inference rule** for the Hoare implication.

**Definition 16.4.** The composition rule covers the task of agreeing correctness proofs of two consecutive segments  $S_1$  and  $S_2$ . Notation:  $S_1 : S_2$  stands for the composite segment consisting of  $S_1$  followed by  $S_2$ . Suppose also that we have already established individual correctness of  $S_1$  and  $S_2$  with respect to *matching conditions*, i.e.  $p\{S_1\}q$  and  $q\{S_2\}r$  both hold. Then

$$\frac{p\{S_1\}q}{q\{S_2\}r} \\ \hline p\{S_1:S_2\}r$$

Definition 16.5. A program segment "if condition then S" is treated by the inference rule

 $\begin{array}{c} (p \land condition) \{S\}q \\ \hline (p \land \neg condition) \to q \\ \hline p\{ \textbf{if condition then S} \}q \end{array}$ 

**Example 16.6.** Show that "if x > y then y := x" is correct with respect to the initial assertion **T** (i.e. *true*) and the final assertion  $y \ge x$ . Again, termination is obvious. According to the standard semantics of "if ... then" operator, both premises of the rule 16.5 take place, i.e.  $(\mathbf{T} \land x > y)\{y := x\}y \ge x$  and  $(\mathbf{T} \land \neg x > y) \rightarrow y \ge x$ . Therefore we can conclude  $\mathbf{T}\{\text{if } x > y \text{ then } y := x\}y \ge x$ .

**Definition 16.7.** A program segment "if condition then  $S_1$  else  $S_2$ " is treated by the inference rule

$$\frac{(p \land condition)\{S_1\}q}{(p \land \neg condition)\{S_2\}q}$$

$$p\{\text{if condition then } S_1 \text{ else}S_2\}q$$

**Example 16.8.** Show that "if x < 0 then abs := -x else abs := x" is correct with respect to the initial assertion **T** and the final assertion abs = |x|. Termination is obvious. For the partial correctness check the premises of the rule 16.7. (**T**  $\land x < 0$ ){abs := -x}abs = |x| and (**T**  $\land x \ge 0$ ){abs := x}abs = |x| both hold, therefore, by 16.7, the corresponding Hoare implication **T**{if x < 0 then abs := -x else abs := x}(abs = |x|) is true.

**Definition 16.9.** Partial correctness of a loop segment "while condition S" is proven by induction on the counter *i*. The induction proposition p(i) is called a **loop invariant**. The rule of inference is

 $\frac{(p \land condition)\{S\}p}{p\{\textbf{while condition } S\}(\neg condition \land p)}$ 

**Example 16.10.** The *factorial* example from Section 3.5.

Homework assignments. (due Friday 03/02).

16A:Rosen3.5-2; 16B:Rosen3.5-4; 16C:Rosen3.5-12.