



PROVING THINGS ABOUT CONCURRENT PROGRAMS

Lecture 23 – CS2110 – Fall 2010

Overview

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- Last time we looked at techniques for proving things about recursive algorithms
 - ▣ We saw that in general, recursion matches with the notion of an inductive proof
- How can one reason about a concurrent algorithm?
 - ▣ We still want proofs of correctness
 - ▣ Techniques aren't identical but we do use induction

Safety and Liveness

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- When a program uses multiple threads, we need to worry about many things
 - ▣ Are concurrent memory accesses correctly synchronized?
 - ▣ Do the threads “interfere” with one-another?
 - ▣ Can a deadlock arise?
 - ▣ What if some single thread gets blocked but the others continue to run?
 - ▣ Could an infinite loop arise in which threads get stuck running, but making no progress?

Safety and Liveness

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- Leslie Lamport suggested that we think about the question in terms of *safety* and *liveness*
 - ▣ A program is *safe* if nothing bad happens. The guarantee that concurrently accessed memory will be locked first is a *safety property*.
 - The property is also called **mutual exclusion**
 - ▣ A program is *live* if good things eventually happen. The guarantee that all threads get to make progress is a *liveness property*

Proper synchronization

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- Consider a program with multiple threads in it
 - ▣ Perhaps threads T1 and T2
 - ▣ They share some objects
- First, we need to ask if the shared objects are **thread safe**
 - ▣ Every access protected by `synchronized() { ... }`

Critical section example

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Thread A: Swap($X[i]$, $Y[j]$)

□ Suppose $i=3$, $j=7$

1. $tmp = X[i];$
2. $X[i] = X[j];$
3. $X[j] = tmp;$

Thread B : Swap($X[i]$, $Y[j]$)

□ same indicies

4. $tmp = X[i];$
5. $X[i] = X[j];$
6. $X[j] = tmp;$

□ Two swaps on the same items... so at the end we should be back where we started, right?

Critical section example

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Thread A: Swap(X[i], Y[j])

Thread B : Swap(X[i], Y[j])

□ Suppose $i=3, j=7$

1. `tmp = X[i];`
2. `X[i] = X[j];`
3. `X[j] = tmp;`

□ same indicies

4. `tmp = X[i];`
5. `X[i] = X[j];`
6. `X[j] = tmp;`

□ What if thread B runs (entirely) in between the last two lines of thread A?

Critical section example

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Thread A: Swap($X[i]$, $Y[j]$)

Thread B : Swap($X[i]$, $Y[j]$)

□ Suppose $i=3$, $j=7$

1. $tmp = X[i];$
2. $X[i] = X[j];$
3. $X[j] = tmp;$

□ same indicies

4. $tmp = X[i];$
5. $X[i] = X[j];$
6. $X[j] = tmp;$

- We end up with $X[i] = X[j]$ and $X[j]$'s old value is lost!
- With other values for i, j and other execution orderings can lose $X[j]$ or cause other kinds of problems

Hardware needs synchronization too!

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- As we saw last week, the hardware itself may malfunction if we omit synchronization!
 - ▣ Modern CPUs sometimes reorder operations to execute them faster, usually because some slow event (like fetching something from memory) occurs, and leaves the CPU with time to kill
 - ▣ So it might look ahead and find some stuff that can safely be done a bit early

Hardware needs synchronization too!

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- Without synchronization locks, if a thread updates objects the thread itself always sees the exact updates in the order they were done
- But other threads on other cores could see them out of order and could see some updates but not others

Interleavings

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- Suppose that a program correctly locks all accesses to shared objects
- Would it now be safe?
- Issue that arises involves *interleavings*

Interleavings

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- Suppose threads A and B are executing
- A updates Object X, and then B changes X
 - ▣ Was this order “enforced by the program” or could it be an accident of thread scheduling?
- Ideally, when threads interact we would like to control ordering so that it will be predictable

Determinism

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- A program is *deterministic* if it produces the identical results every time it is run with identical input
 - ▣ This is desirable
- A program is *non deterministic* if the same inputs sometimes result in different outcomes
 - ▣ This is confusing and can signal problems

Linearizability

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- Concept was proposed by Wing and Herlihy
 - ▣ Start with your concurrent program
 - ▣ But prove that it behaves just like some non-concurrent program that does the same operations in some “linear” order
 - Idea behind proof: if the effect of two executions is the same, then we can treat them as equivalent
- Program is concurrent yet acts deterministic
- Not all programs are linearizable

We also worry about **Deadlock**

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- Deadlock occurs if two or more threads are unable to execute because each is waiting for the other to do something, and both are blocked
- This is typically a buggy situation and hence we also need to prove that our concurrent code can't deadlock

Deadlock

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- Recall from last week

- Deadlock depends on four conditions
 - ▣ A wait-for cycle
 - ▣ Locks that are held until the thread finishes what it wants to do, not released
 - ▣ No preemption of locks
 - ▣ Mutual exclusion

Example: Deadlock avoidance

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- Suppose that threads acquire locks in some standard order. *Thm: deadlock cannot occur!*
 - ▣ Slightly oversimplified proof: A deadlock means that there is some cycle of threads A, B.... T each waiting for the next to take some action.
 - ▣ Consider thread A and assume A holds lock X_a .
 - A is waiting on B: A wants a lock X_b and B holds that lock.
 - Now look at B: it holds X_b and wants X_c .
 - We eventually get to thread T that holds X_t and wants X_a
 - But per our rules $X_a < X_b < \dots X_t < X_a$: a contradiction! QED
 - ▣ Notice that this is similar to an inductive argument

Induction connection?

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- Base case focuses on two threads, A and T
 - A is holding X_A and wants X_T
 - T is holding X_T and will wait for A
 - But T is violating policy. So we can't deadlock with two threads

- Induction case: assume no deadlocks with $n-1$ threads. Show no deadlocks with n threads.
 - We won't write this out in logic, but we could.

Paris traffic circles: Deadlock in action

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- Paris has a strange rule at some traffic circles: *priorité a droite*
- Traffic circles around, say, the Arc de Triomphe
- Roads enter from the right
- You must yield to let them enter



Paris traffic circle: *priorité à droite*

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- An issue at Place d'Etoile and Place Victor Hugo (rest of France uses *priorité à gauche*)
- Think of cars as threads and “space” as objects
 - ▣ If thread A occupies a space that thread B wishes to enter, then B waits for A
 - ▣ Under this rule, deadlocks can form!
- To see this, look for a wait-for cycle

Why is *priorité à droite* a bad rule?

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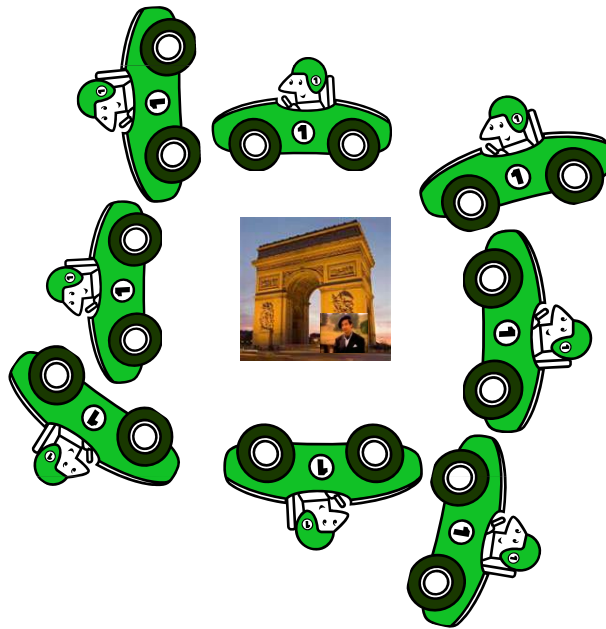
Arc de Triomphe

French guy

French Traffic

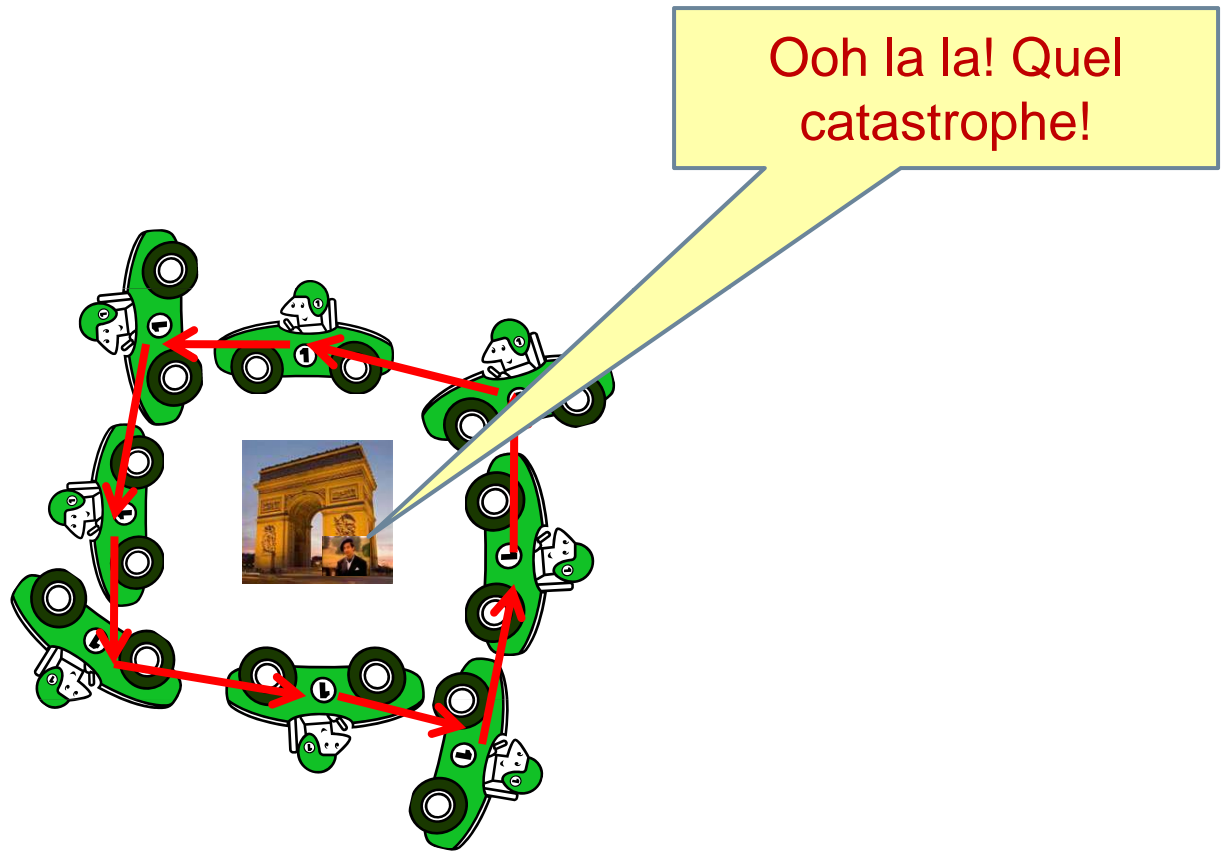
Why is *priorité à droite* a bad rule?

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Why is *priorité à droite* a bad rule?

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But why is this specific to *priorité a droite*?

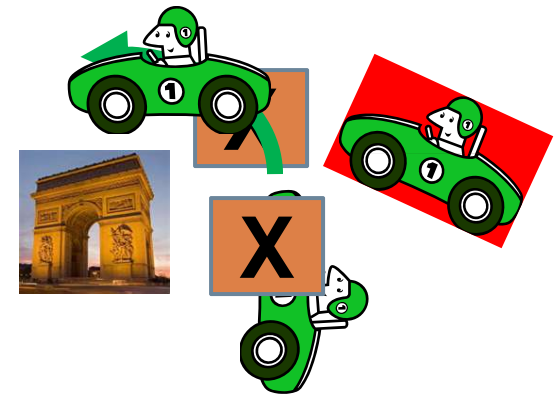
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- With *priorité a gauche* cars already in the circle have priority over cars trying to enter
- Cars can drive around the circle until each car gets to its desired exit road and the traffic drains away
 - ▣ In fact can drive around and around if they like
 - ▣ Deadlock can't arise!

Inductive proof?

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- Again, lends itself to an inductive proof
- Here's the key step in graphical form:
 - ▣ Assume we are not yet deadlocked: there is at least one space "X" free on the traffic circle
 - ▣ Red and Green cars both want to advance into X
 - ▣ Green is on the left, so it wins
 - ▣ This leaves space behind it



As a proof

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- Two base cases
 - Traffic circle is “fully populated”.
 - Then traffic can rotate around circle until cars reach their exit streets and leave
 - Traffic circle has at least one gap
 - Priority-a-gauche ensures that the in-circle traffic will claim it, not the car contending to enter from right

As a proof

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- Inductive case
 - Assumes that “chains” of $n-1$ cars are deadlock free
 - Add one car
 - If you add it in the circle, it waits for the car in front to move (which it will, by induction), then follows it
 - If you add it outside the circle, it can only enter if there is no contention with any car in the circle

- We conclude: the circle itself won't deadlock!

But are cars happy?

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- A car trying to enter might have bad luck and wait... forever!
 - ▣ This is called « starvation »

Starvation

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- We say that a thread **starves** if it can't execute
 - ▣ A common reason: some thread locks a resource but forgets to unlock it
 - ▣ Not a deadlock because only one thread is stuck

What did this example show?

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- We can sometimes prevent deadlock by controlling the “order” that contending threads grab resources
 - ▣ Priorite a gauche is such a rule.
 - ▣ But this also creates risk of starvation
- Ensuring that a system is both deadlock and starvation free requires clever design

Recap

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- To prove a concurrent program correct we need to
 - ▣ Prove that the shared memory is accessed safely
 - ▣ Prove that threads can make useful progress
 - No deadlocks or livelocks or starvation
 - ▣ Guarantee determinism (optional, but useful)

- In practice this is very hard to do because of the vast number of possible interleavings

Debugging concurrent programs

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- When we add threads to a program, or create a threaded program, debugging becomes more challenging
 - ▣ Without threads we think only about the “straight line” execution of our code
 - ▣ With threads need to think about all the orderings that can arise as they get scheduled

Bugs in concurrent programs



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- In addition to regular kinds of bugs they often have bugs specific to concurrency!
 - ▣ Non-determinism and race conditions
 - ▣ Deadlock, livelock, starvation
 - ▣ Harder to reason about

Bugs in concurrent programs



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- Bruce Lindsay once suggested that there are two kinds of bugs
 - ▣ Bohrbugs are like the Bohr model of the nucleus: we can track them down and exterminate them
 - Most deterministic, non-concurrent programs only have Bohrbugs and this is a good thing
 - ▣ Heisenbugs are hard to pin down: the closer you look the more they shift around, like a Heisenberg model of the atomic nucleus (a “cloud”)

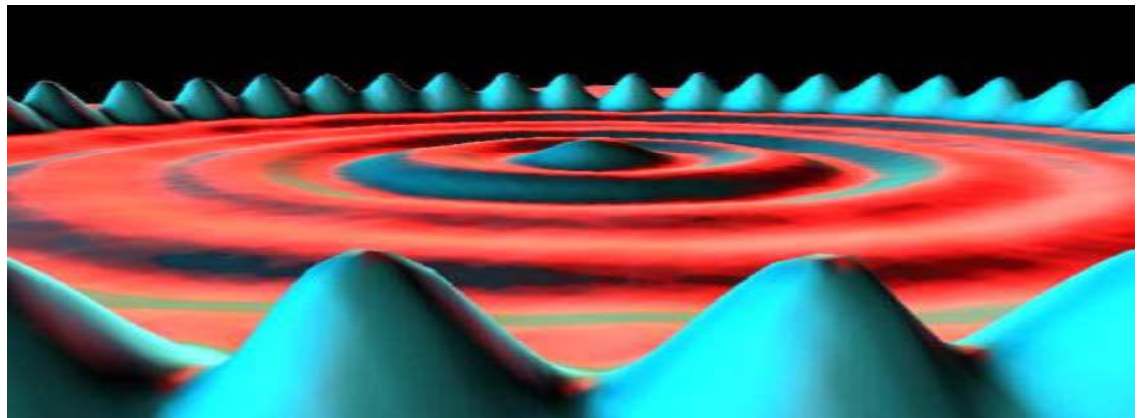
Bugs in concurrent programs



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- Concurrent programs often have latent Heisenbugs
 - ▣ Something that happened a while ago was the cause
 - ▣ And the thread scheduling order may determine when you actually see the crash!

*Where's the
electron?*



Bugs in concurrent programs



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- Concurrent programs notorious for Heisenbugs
- You tend to focus on their eventual effect
 - ▣ But that was the symptom, not the cause!
 - ▣ You work endlessly but aren't actually even looking at the thing that caused the problem!
- And the debugger might cause the problem to shift around

Adding threads to unsafe code

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- Modern fad: Adding threading to a program so that it can benefit from multicore hardware
 - ▣ Start with a program that was built without threads. Then introduce threads and synchronization
 - ▣ If you weren't the original designer, this is a risky way to work!



***Risky style?
I am liking concurrency
very much!***

Our recommendations?

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- Threads are an unavoidable evil
 - ▣ We need them for performance and responsiveness
 - ▣ But they make it (much) harder to prove things about our programs
 - ▣ Must use them cautiously and in very controlled ways
- **Linearizability** can greatly simplify analysis
- Use **inductive style of proofs** to reason about chains of threads that wait for one-another