

# PRIORITY QUEUES AND HEAPS

Lecture 17  
CS2110 Fall 2009

## The Bag Interface

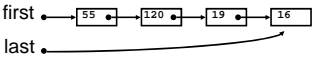
□ A Bag:

```
interface Bag<E> {
    void insert(E obj);
    E extract(); //extract some element
    boolean isEmpty();
}
```

Examples: Stack, Queue, PriorityQueue

## Stacks and Queues as Lists

- Stack (LIFO) implemented as list
  - insert(), extract() from front of list
- Queue (FIFO) implemented as list
  - insert() on back of list, extract() from front of list
- All Bag operations are O(1)



## Priority Queue

- A Bag in which data items are Comparable
- lesser elements (as determined by compareTo()) have higher priority
- extract() returns the element with the highest priority = least in the compareTo() ordering
- break ties arbitrarily

## Priority Queue Examples

- Scheduling jobs to run on a computer
  - default priority = arrival time
  - priority can be changed by operator
- Scheduling events to be processed by an event handler
  - priority = time of occurrence
- Airline check-in
  - first class, business class, coach
  - FIFO within each class

## java.util.PriorityQueue<E>

```
boolean add(E e) {...} //insert an element (insert)
void clear() {...} //remove all elements
E peek() {...} //return min element without removing
// (null if empty)
E poll() {...} //remove min element (extract)
// (null if empty)
int size() {...}
```

### Priority Queues as Lists

- Maintain as **unordered** list
  - `insert()` puts new element at front -  $O(1)$
  - `extract()` must search the list -  $O(n)$
- Maintain as **ordered** list
  - `insert()` must search the list -  $O(n)$
  - `extract()` gets element at front -  $O(1)$
- In either case,  $O(n^2)$  to process  $n$  elements

Can we do better?

### Important Special Case

- Fixed number of priority levels  $0, \dots, p - 1$
- FIFO within each level
- Example: airline check-in

- `insert()` - insert in appropriate queue -  $O(1)$
- `extract()` - must find a nonempty queue -  $O(p)$

### Heaps

- A *heap* is a concrete data structure that can be used to implement priority queues
- Gives better complexity than either ordered or unordered list implementation:
  - `insert()`:  $O(\log n)$
  - `extract()`:  $O(\log n)$
- $O(n \log n)$  to process  $n$  elements
- Do not confuse with *heap memory*, where the Java virtual machine allocates space for objects - different usage of the word *heap*

### Heaps

- Binary tree with data at each node
- Satisfies the *Heap Order Invariant*:

The least (highest priority) element of any subtree is found at the root of that subtree

- Size of the heap is "fixed" at  $n$ . (But can usually double  $n$  if heap fills up)

### Heaps

Least element in any subtree is always found at the root of that subtree

```

    graph TD
      4[4] --> 6[6]
      4 --> 14[14]
      6 --> 21[21]
      6 --> 8[8]
      21 --> 22[22]
      21 --> 38[38]
      8 --> 55[55]
      8 --> 10[10]
      14 --> 19[19]
      14 --> 35[35]
      19 --> 20[20]
  
```

Note:  $19, 20 < 35$ : we can often find smaller elements deeper in the tree!

### Examples of Heaps

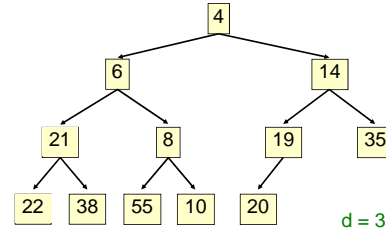
- Ages of people in family tree
  - parent is always older than children, but you can have an uncle who is younger than you
- Salaries of employees of a company
  - bosses generally make more than subordinates, but a VP in one subdivision may make less than a Project Supervisor in a different subdivision

## Balanced Heaps

These add two restrictions:

- Any node of depth  $< d - 1$  has exactly 2 children, where  $d$  is the height of the tree
    - implies that any two maximal paths (path from a root to a leaf) are of length  $d$  or  $d - 1$ , and the tree has at least  $2^d$  nodes
- All maximal paths of length  $d$  are to the left of those of length  $d - 1$

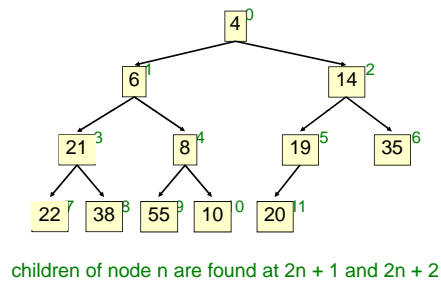
## Example of a Balanced Heap



## Store in an ArrayList or Vector

- Elements of the heap are stored in the array in order, going across each level from left to right, top to bottom
- The children of the node at array index  $n$  are found at  $2n + 1$  and  $2n + 2$
- The parent of node  $n$  is found at  $(n - 1)/2$

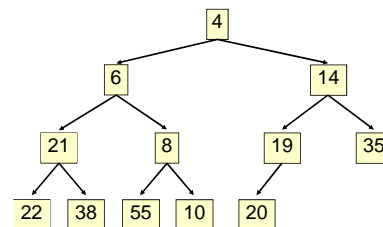
## Store in an ArrayList or Vector

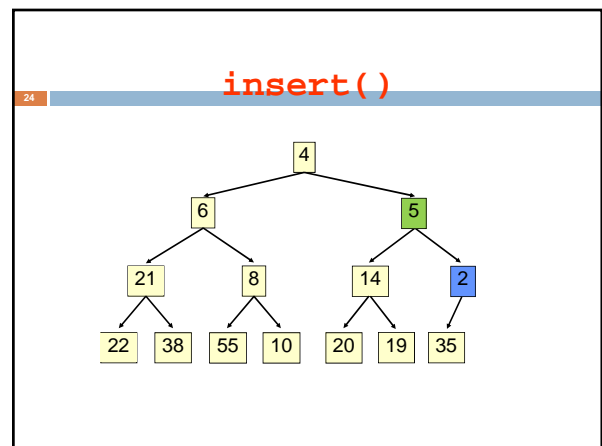
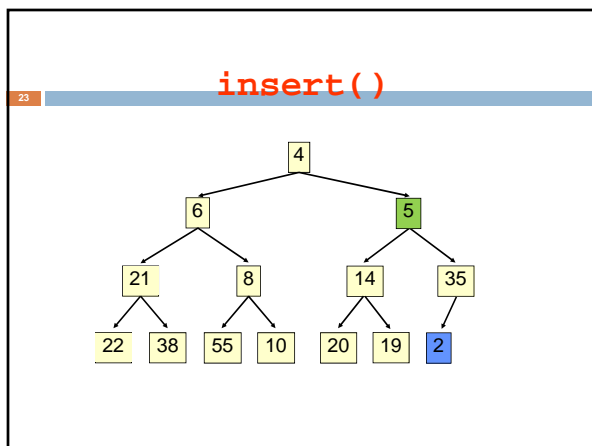
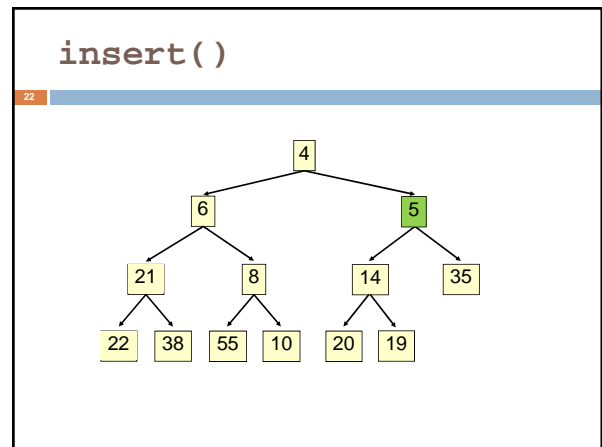
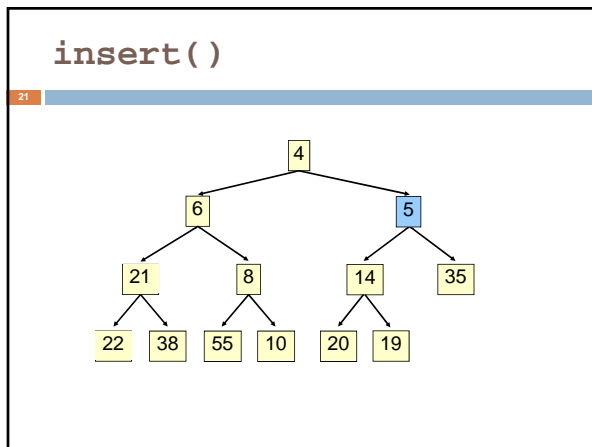
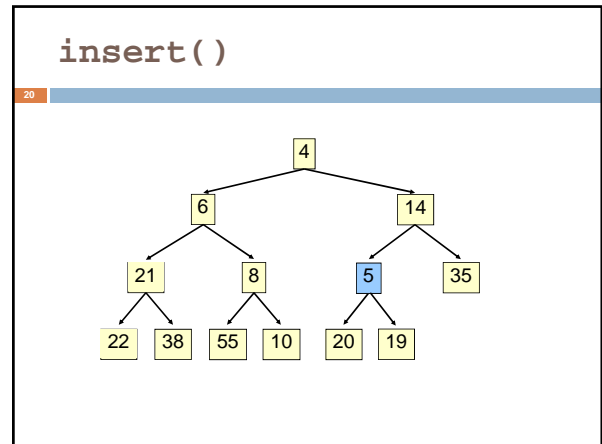
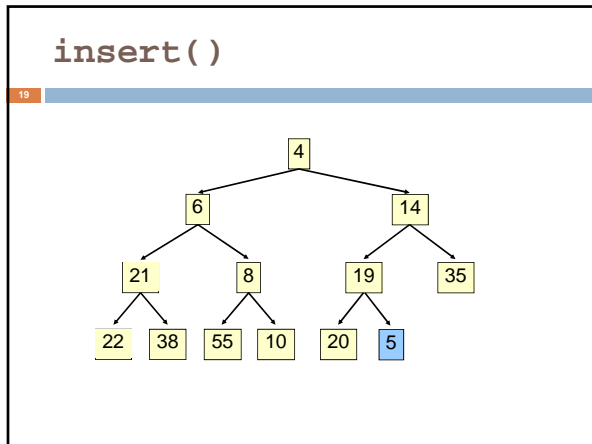


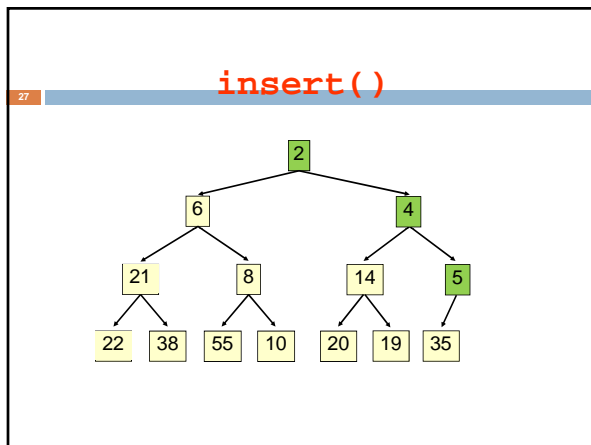
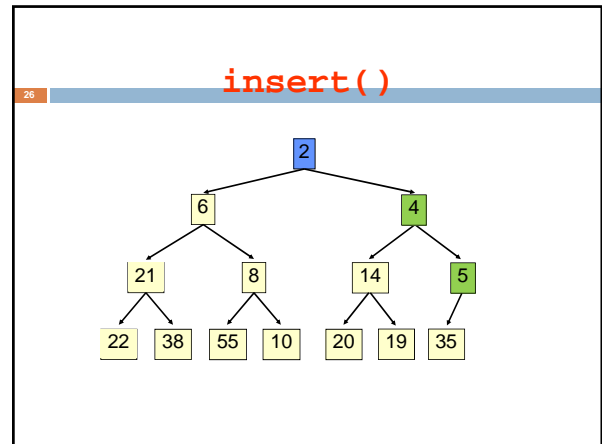
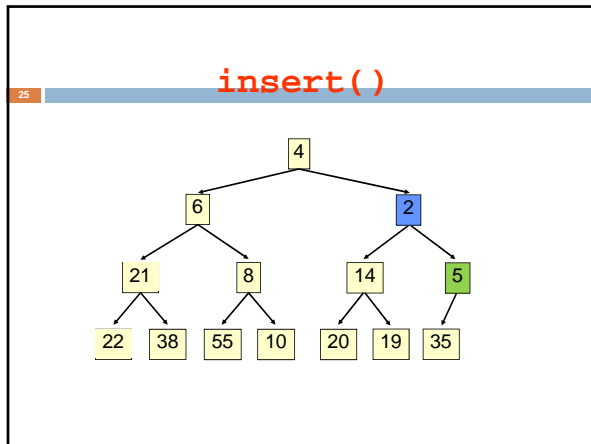
## insert()

- Put the new element at the end of the array
- If this violates heap order because it is smaller than its parent, swap it with its parent
- Continue swapping it up until it finds its rightful place
- The heap invariant is maintained!

## insert()







28 **insert()**

- Time is  $O(\log n)$ , since the tree is balanced
- size of tree is exponential as a function of depth
- depth of tree is logarithmic as a function of size

29 **insert()**

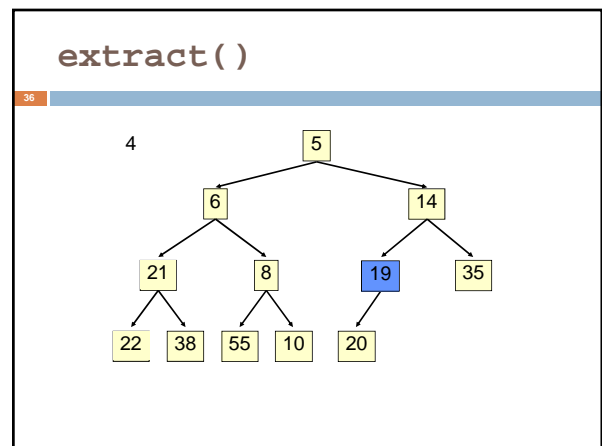
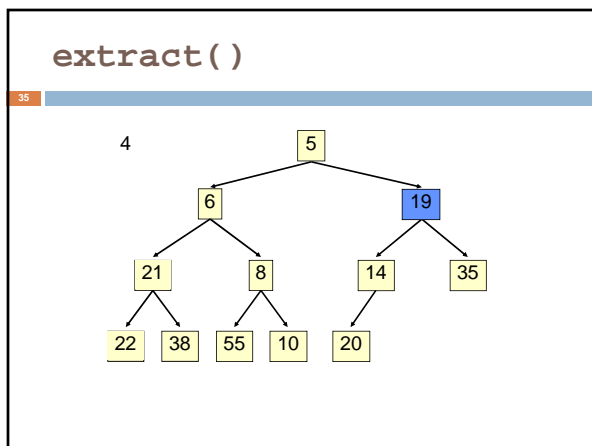
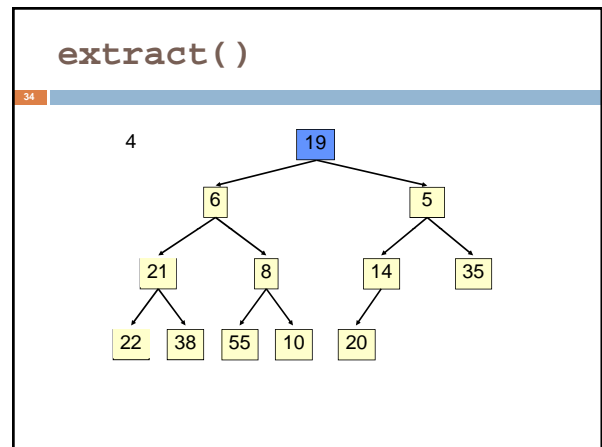
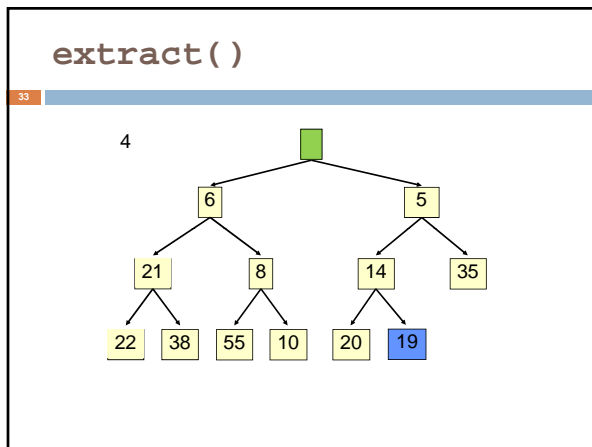
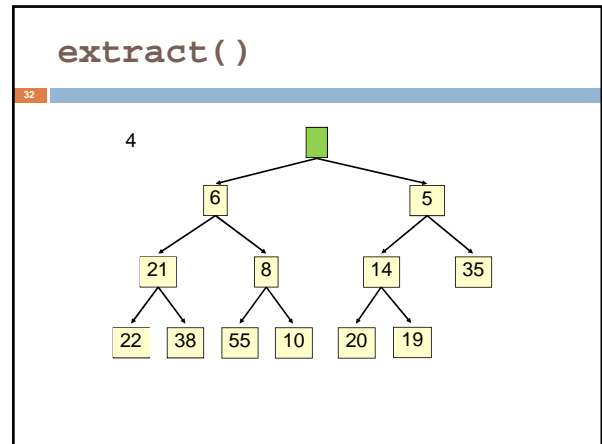
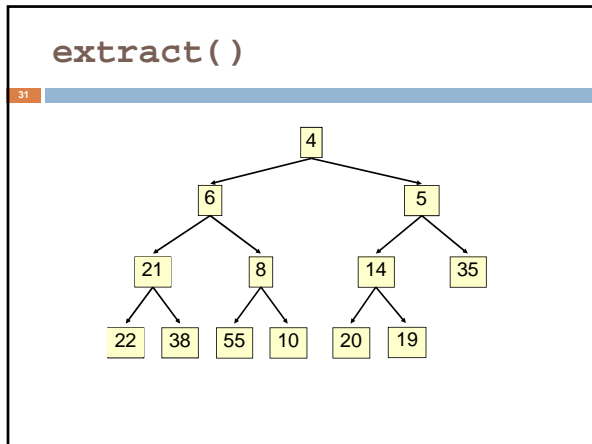
```

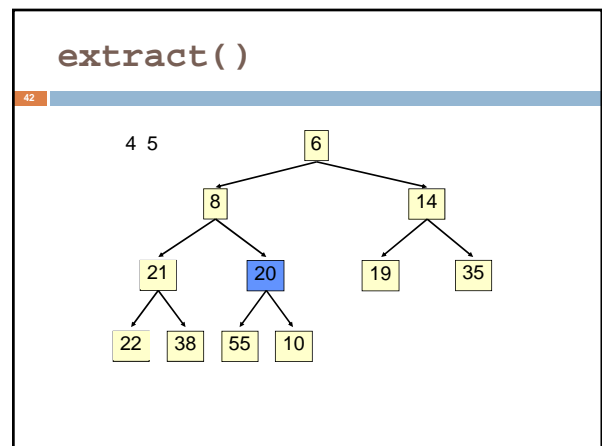
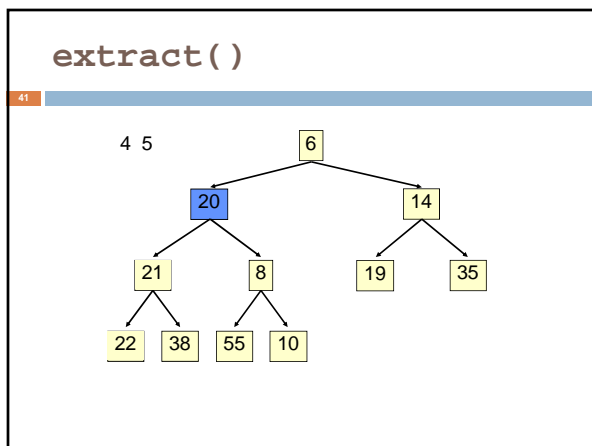
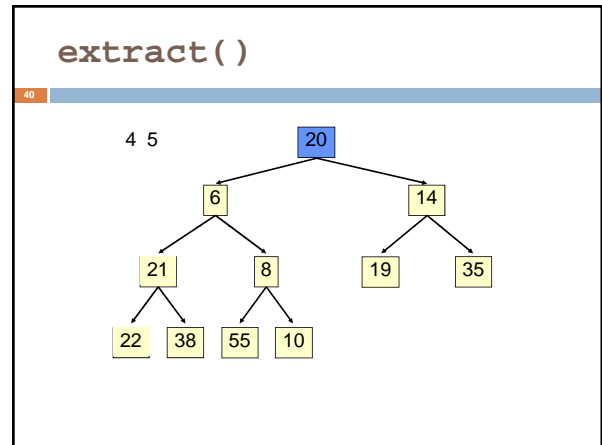
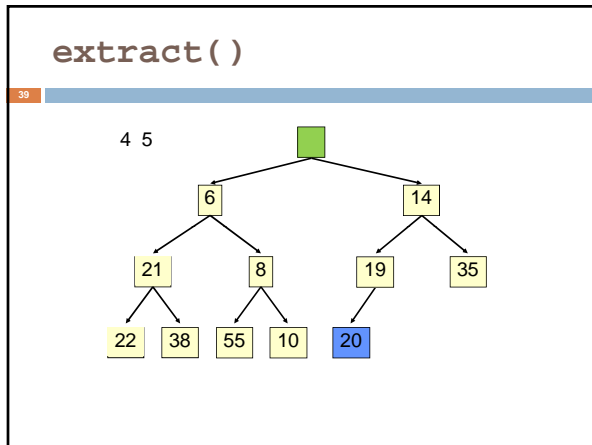
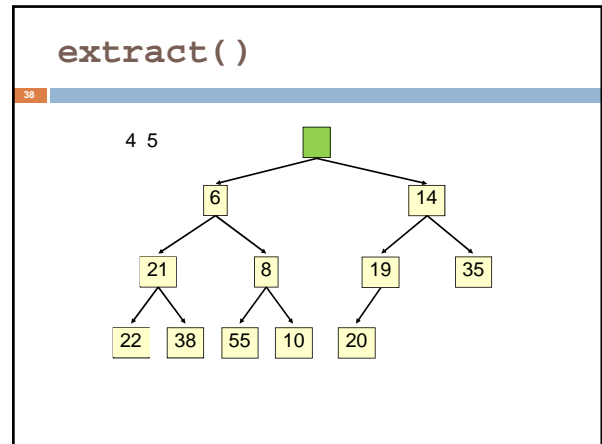
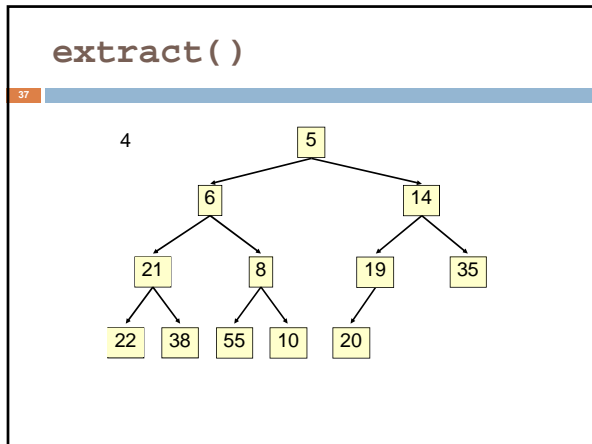
class PriorityQueue<E> extends java.util.Vector<E> {
    public void insert(E obj) {
        super.add(obj); //add new element to end of array
        rotateUp(size() - 1);
    }

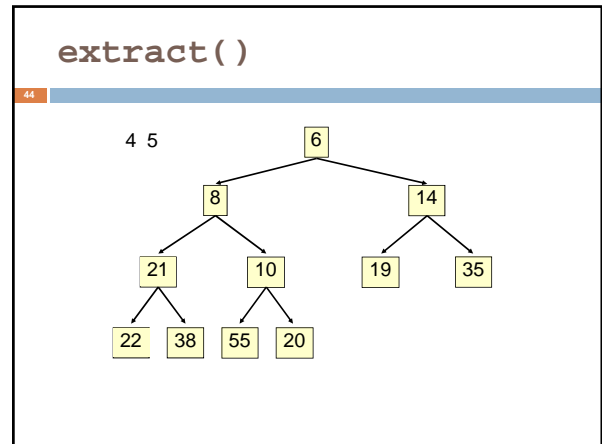
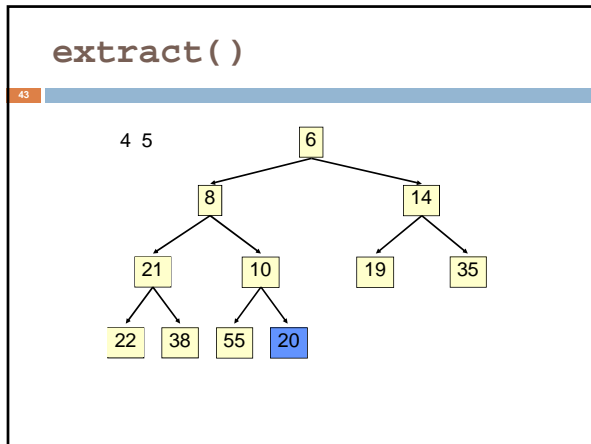
    private void rotateUp(int index) {
        if (index == 0) return;
        int parent = (index - 1)/2;
        if (elementAt(parent).compareTo(elementAt(index)) <= 0)
            return;
        swap(index, parent);
        rotateUp(parent);
    }
}
    
```

30 **extract()**

- Remove the least element – it is at the root
- This leaves a hole at the root – fill it in with the last element of the array
- If this violates heap order because the root element is too big, swap it down with the smaller of its children
- Continue swapping it down until it finds its rightful place
- The heap invariant is maintained!







### extract ()

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- Time is  $O(\log n)$ , since the tree is balanced

### extract ()

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```

public E extract() {
    if (size() == 0) return null;
    E temp = elementAt(0);
    setElementAt(elementAt(size() - 1), 0);
    setSize(size() - 1);
    rotateDown(0);
    return temp;
}

private void rotateDown(int index) {
    int child = 2*(index + 1); //right child
    if (child >= size())
        || elementAt(child - 1).compareTo(elementAt(child)) < 0)
        child -= 1;
    if (child >= size()) return;
    if (elementAt(index).compareTo(elementAt(child)) <= 0)
        return;
    swap(index, child);
    rotateDown(child);
}
  
```

### HeapSort

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Given a `Comparable[]` array of length  $n$ ,

- Put all  $n$  elements into a heap –  $O(n \log n)$
- Repeatedly get the min –  $O(n \log n)$

```

public static void heapSort(Comparable[] a) {
    PriorityQueue<Comparable> pq
    = new PriorityQueue<Comparable>();
    for (Comparable x : a) { pq.insert(x); }
    for (int i = 0; i < a.length; i++) { a[i] = pq.extract(); }
}
  
```

### PQ Application: Simulation

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□ Example: Probabilistic model of bank-customer arrival times and transaction times, how many tellers are needed?

- Assume we have a way to generate random inter-arrival times
- Assume we have a way to generate transaction times
- Can simulate the bank to get some idea of how long customers must wait

**Time-Driven Simulation**

- Check at each *tick* to see if any event occurs

**Event-Driven Simulation**

- Advance clock to next event, skipping intervening *ticks*
- This uses a PQ!